

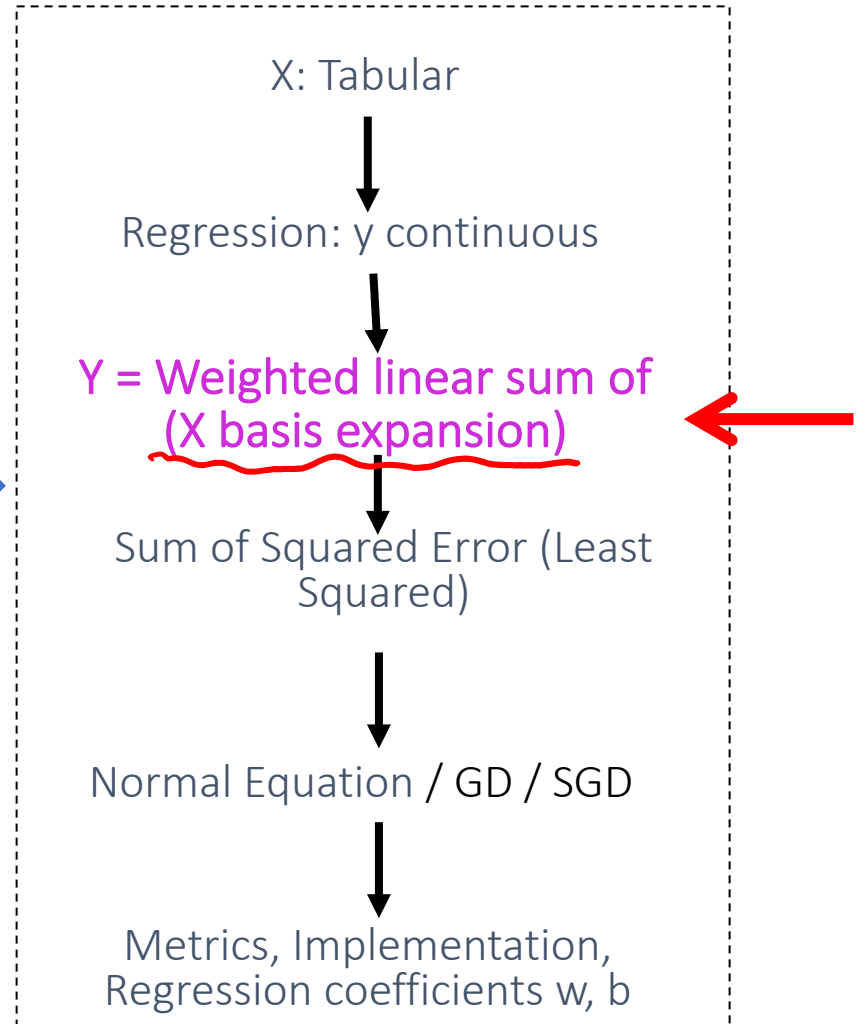
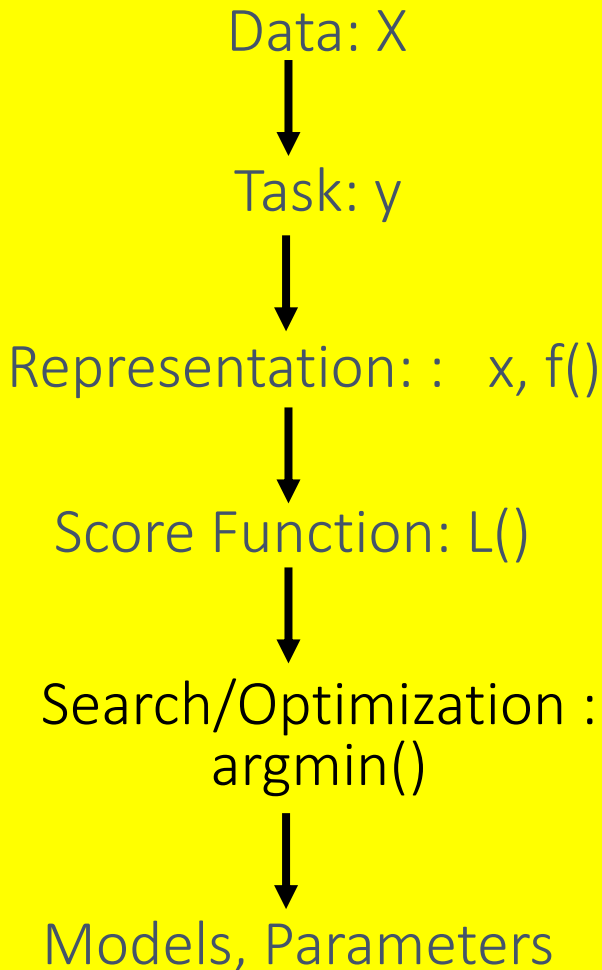
# UVA CS 4774: Machine Learning

## Lecture 5: Linear Regression with Basis Functions Expansion

Dr. Yanjun Qi

University of Virginia  
Department of Computer Science

# Today : Multivariate (non-) Linear Regression with Basis Expansion



$$\hat{y} = \theta_0 + \sum_{j=1}^m \theta_j \varphi_j(x) = \underline{\varphi(x)^T} \theta$$

# Linear Regression with non-linear basis functions

- LR can deal with nonlinear relationships

$$\hat{y} = \theta^T \mathbf{x} \quad \longrightarrow \quad \hat{y} = \theta_0 + \sum_{j=1}^m \theta_j \varphi_j(\mathbf{x}) = \theta^T \varphi(\mathbf{x})$$

$$\vec{\theta} = [\theta_0, \theta_1, \dots, \theta_m]^T$$

$$\vec{\Phi} = [1, \varphi_1(x), \dots, \varphi_m(x)]^T$$

# LR with non-linear basis functions

- Free to design basis functions (e.g., non-linear features:

Here  $\varphi_j(x)$  are [predefined] basis functions (also  $\varphi_0(x)=1$  )

- E.g.: polynomial regression with degree up-to two (d=2) :

$$\varphi(x) := [1, x, x^2]^T$$

Linear  $\vec{x} : [1, x]^T$





# Polynomial basis based Regression

<https://colab.research.google.com/github/jakevdp/PythonDataScienceHandbook/blob/master/notebooks/05.06-Linear-Regression.ipynb>

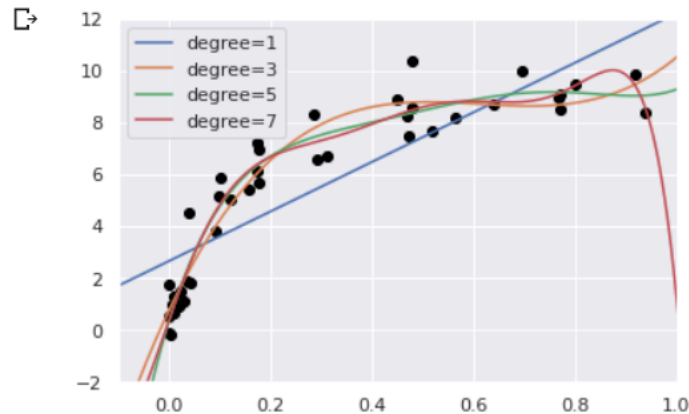
My google-colab modified version: ( I will cell-run it during class)

[https://colab.research.google.com/drive/1gKEk0BuVORnpw\\_5jQ10wY1ZkA2mSXEAG?usp=sharing](https://colab.research.google.com/drive/1gKEk0BuVORnpw_5jQ10wY1ZkA2mSXEAG?usp=sharing)

```
▶ %matplotlib inline
import matplotlib.pyplot as plt
import seaborn; seaborn.set() # plot formatting

X_test = np.linspace(-0.1, 1.1, 500)[: , None]

plt.scatter(X.ravel(), y, color='black')
axis = plt.axis()
for degree in [1, 3, 5, 7]:
    y_test = PolynomialRegression(degree).fit(X, y).predict(X_test)
    plt.plot(X_test.ravel(), y_test, label='degree={0}'.format(degree))
plt.xlim(-0.1, 1.0)
plt.ylim(-2, 12)
plt.legend(loc='best');
```

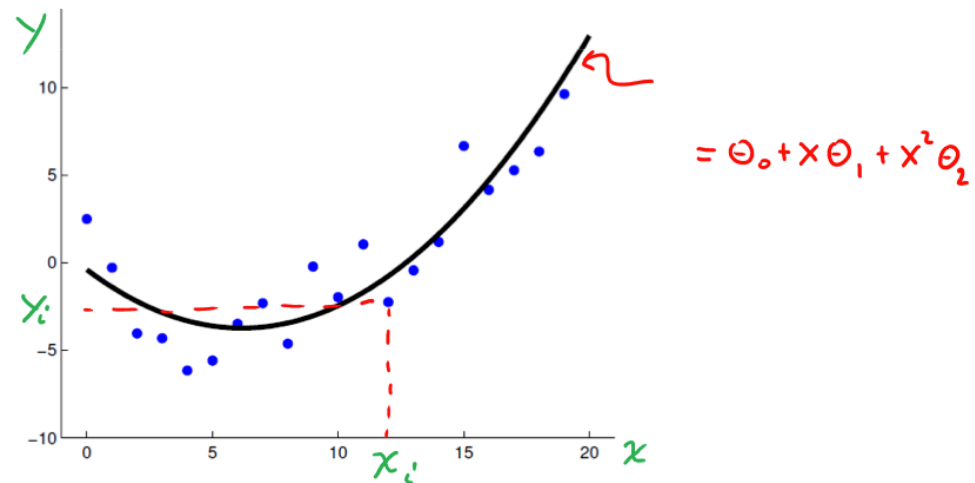
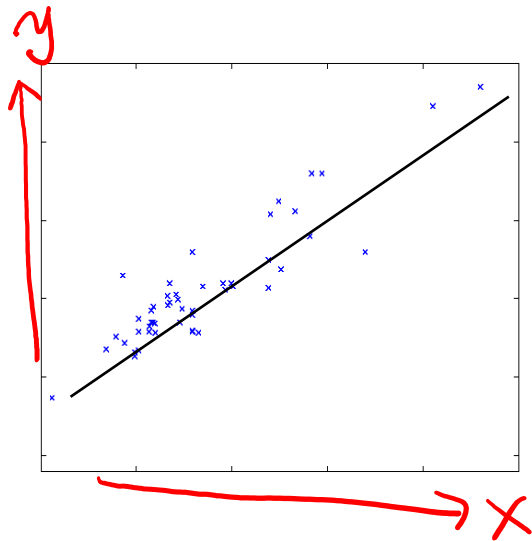


e.g. (1) polynomial regression

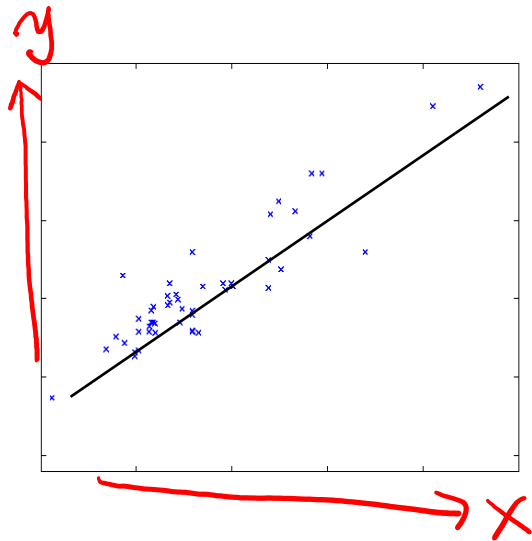
$$\hat{y} = \theta^T \mathbf{x}$$



$$\hat{y} = \theta^T \varphi(\mathbf{x})$$

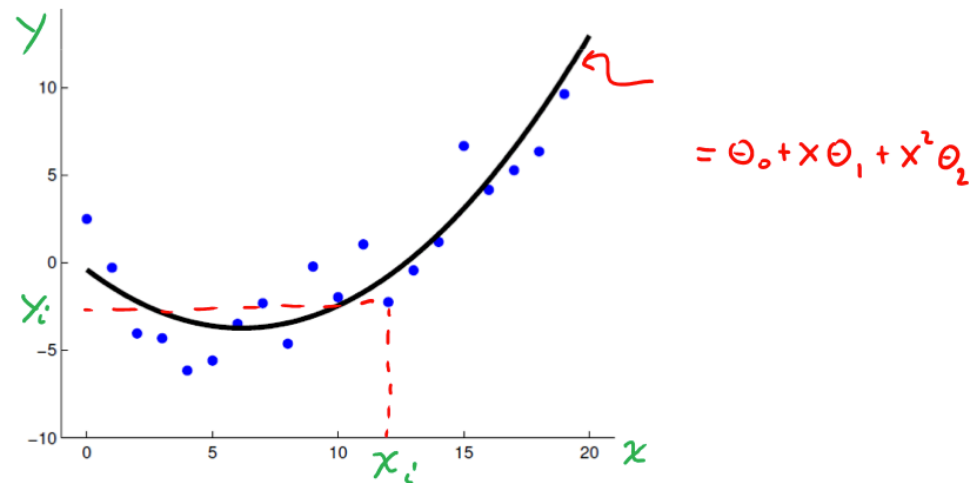


$$\hat{y} = \theta^T \mathbf{x}$$



$$\theta^* = (X^T X)^{-1} X^T \bar{y}$$

$$\hat{y} = \theta^T \varphi(\mathbf{x})$$



$$\theta^* = (\varphi^T \varphi)^{-1} \varphi^T \bar{y}$$

$$\varphi(x) := [1, x, x^2]^T \text{ feature engineering}$$

Linear  $\vec{x} := [1, x]^T$

$$\theta^* = (X^T X)^{-1} X^T \vec{y}$$

$$\sum_{n \times p} = \begin{matrix} 1 \\ 2 \\ \vdots \\ n \end{matrix} \left[ \begin{matrix} \phantom{0} \\ \phantom{0} \\ \phantom{0} \\ \phantom{0} \end{matrix} \right] \xrightarrow{(\varphi+1)}$$

$$\varphi(x) := \begin{bmatrix} 1, x, x^2 \\ \phantom{1} \phantom{x} \phantom{x^2} \\ \phantom{1} \phantom{x} \phantom{x^2} \\ \phantom{1} \phantom{x} \phantom{x^2} \\ \phantom{1} \phantom{x} \phantom{x^2} \end{bmatrix}^T$$

1 2 ... m

$$\theta^* = \underbrace{(\varphi^T \varphi)^{-1}}_{\substack{m \times n \quad n \times n}} \underbrace{\varphi^T \vec{y}}_{\substack{n \times n \quad n \times 1 \quad n \times 1}}$$

$$\varphi(x) = \begin{matrix} 1 \\ 2 \\ 3 \\ \vdots \\ n \end{matrix} \left[ \begin{matrix} \phantom{0} \\ \phantom{0} \\ \phantom{0} \\ \phantom{0} \end{matrix} \right]$$

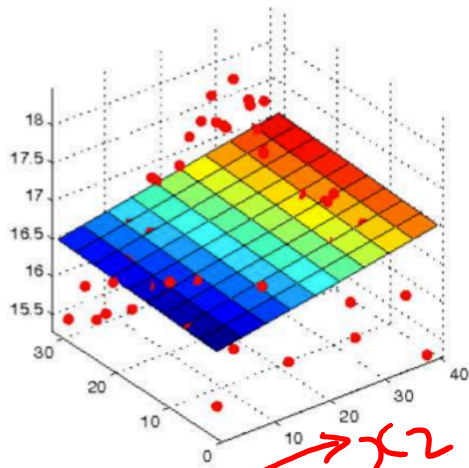
1 ... m

$$\vec{\theta} \in \mathbb{R}^m$$

KEY: when the basis func are given, the problem of learning the parameters from data is still LR.

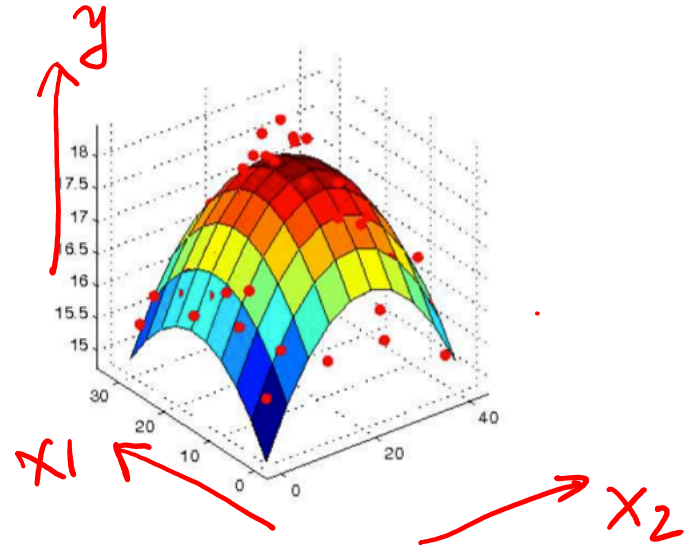
$$\hat{y} = \theta^T \mathbf{x}$$

$$\phi(\mathbf{x}) = [1, x_1, x_2]$$

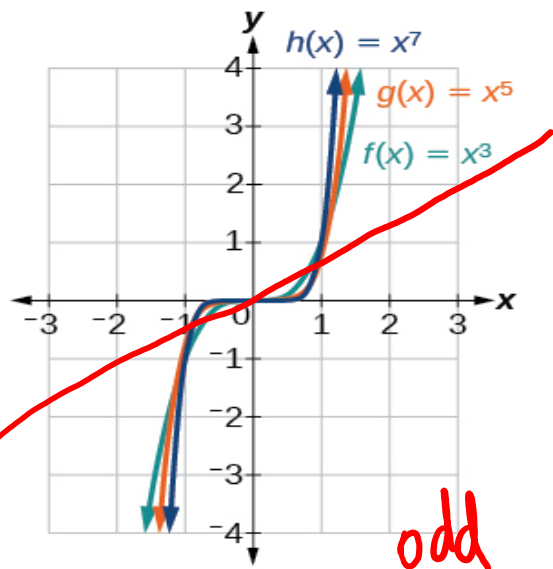
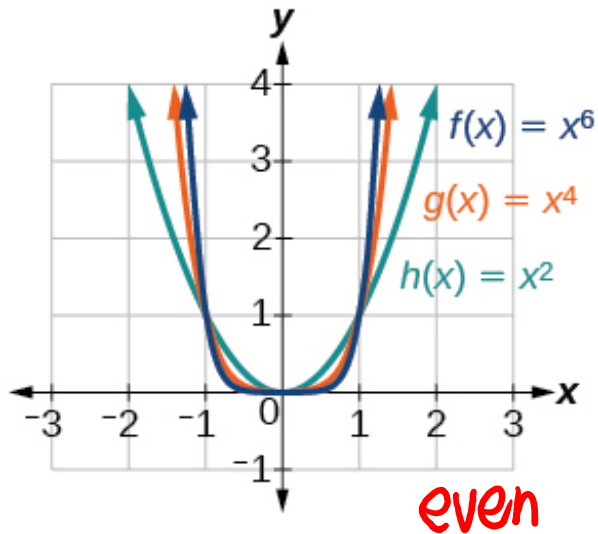


$$\hat{y} = \theta^T \phi(\mathbf{x})$$

$$\phi(\mathbf{x}) = [1, x_1, x_2, x_1^2, x_2^2] \quad , x_1, x_2$$



$$\varphi_j(x) = x^{j-1}$$



My google-colab modified version: ( I will cell-run it)  
[https://colab.research.google.com/drive/1gKEk0BuVO Rnpw\\_5jQ10wY1ZkA2mSXEAG?usp=sharing](https://colab.research.google.com/drive/1gKEk0BuVO Rnpw_5jQ10wY1ZkA2mSXEAG?usp=sharing)

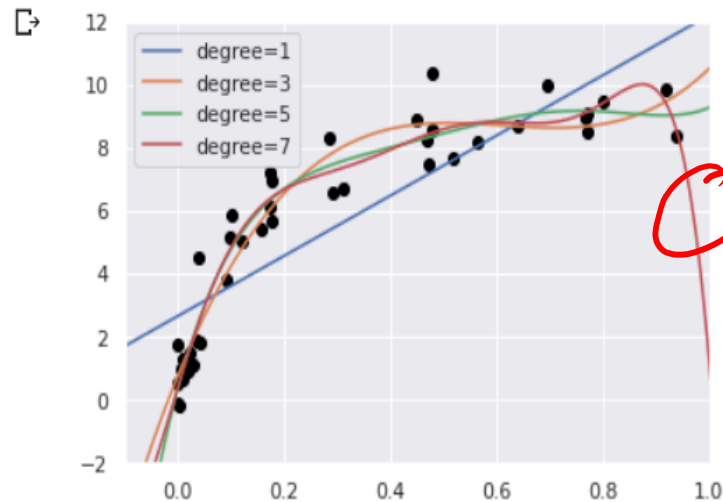
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plt.ylim(-2, 12)
plt.legend(loc='best');

```



$[1, x, x^2, \dots, x^7]$

???

# UVA CS 4774: Machine Learning

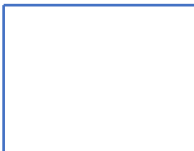
## Lecture 5: Linear Regression with Basis Functions Expansion

### Module 2


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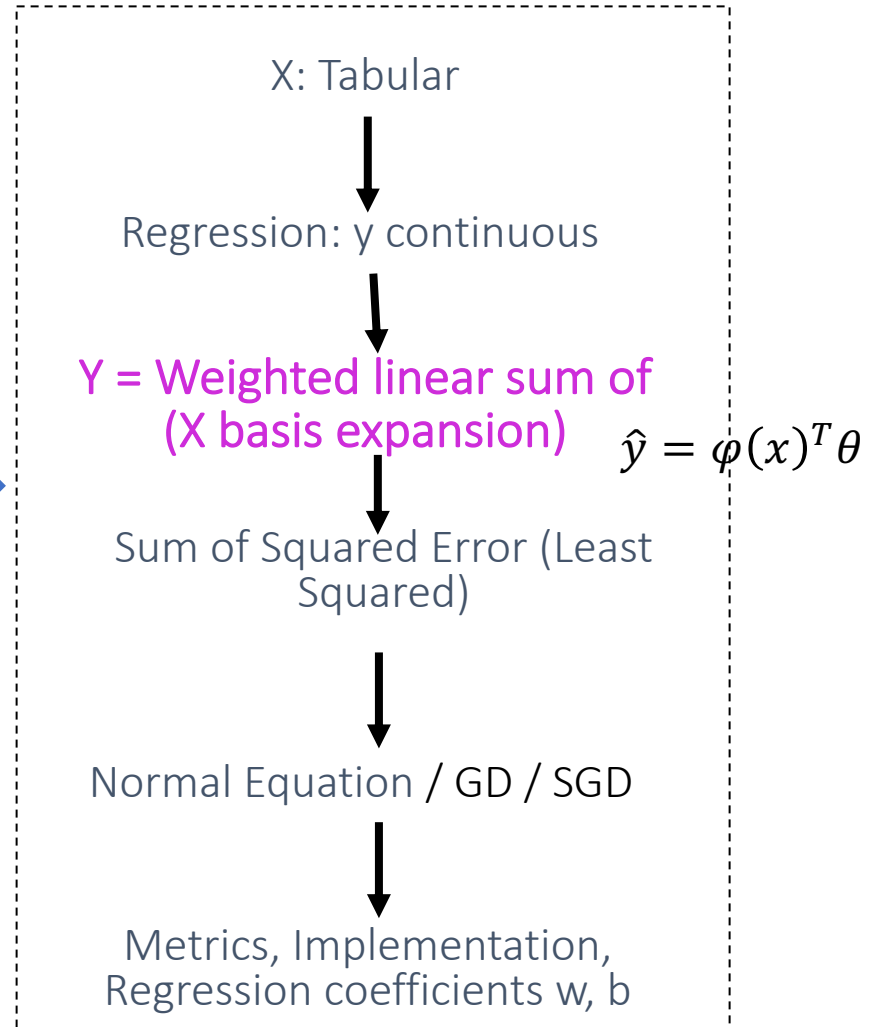
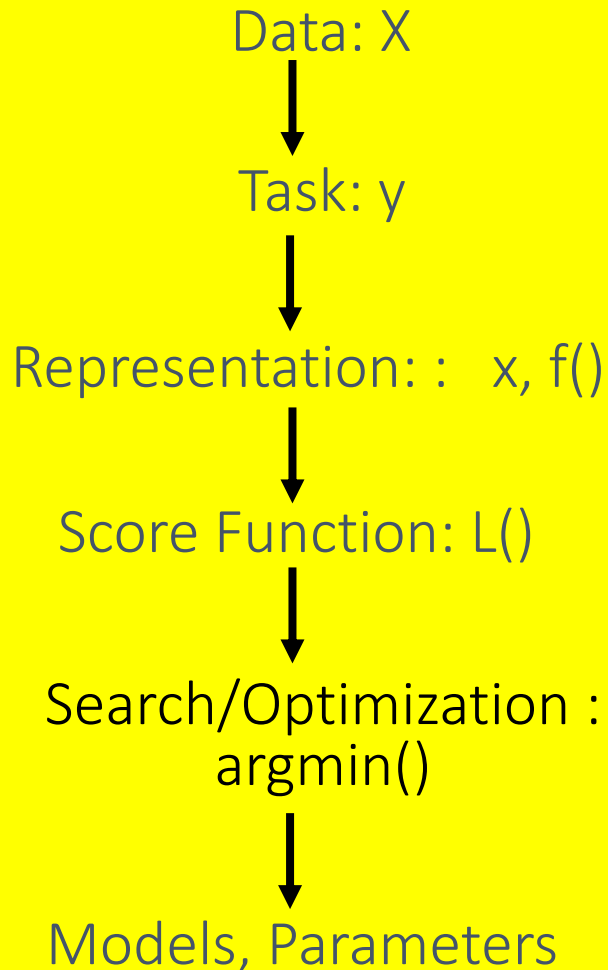

$$\hat{y} = \boldsymbol{\theta}^T \mathbf{x}$$



$$\hat{y} = \boldsymbol{\theta}^T \boldsymbol{\varphi}(\mathbf{x})$$


Many Possible Basis functions

# Recap : Multivariate (non-) Linear Regression with Basis Expansion



$\phi$ : Which and what type?

# Many Possible Basis functions

- There are many basis functions, e.g.:

- Polynomial

$$\varphi_j(x) = x^{j-1}$$

$$[1, x, x^2, x^3, \dots, x^d]$$

- Radial basis functions

$$\varphi_j(x) = \exp\left(-\frac{(x - \mu_j)^2}{2\lambda^2}\right)$$

- Sigmoidal

$$\phi_j(x) = \sigma\left(\frac{x - \mu_j}{s}\right)$$

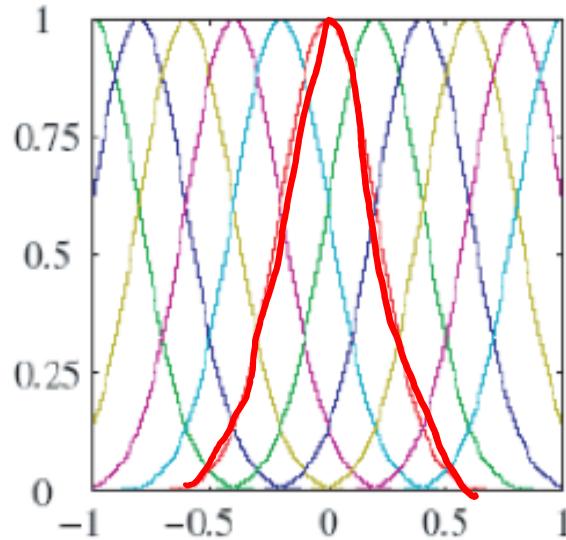
- Splines,

- Fourier,

- Wavelets, etc

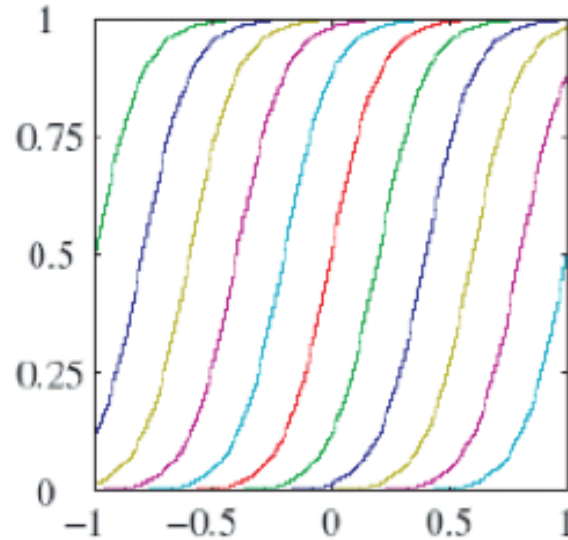
$$\varphi_j(x) = \exp\left(-\frac{(x - \mu_j)^2}{2\lambda^2}\right)$$

$$\phi_j(x) = \sigma\left(\frac{x - \mu_j}{s}\right)$$



RBF

"bell"-Shaped



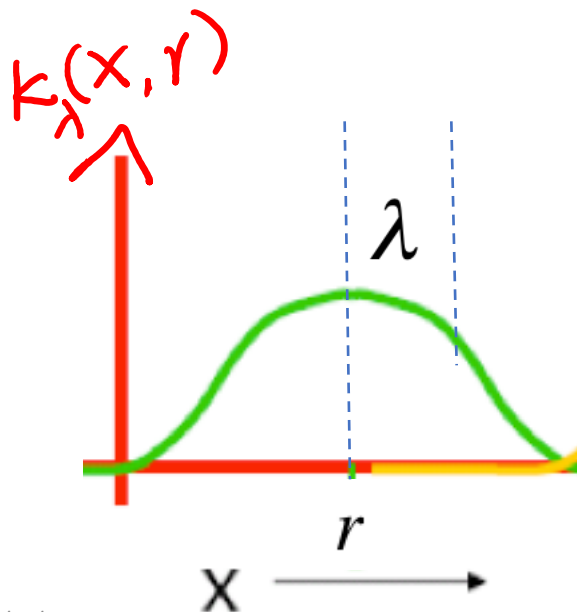
Sigmoid

"S"-Shaped

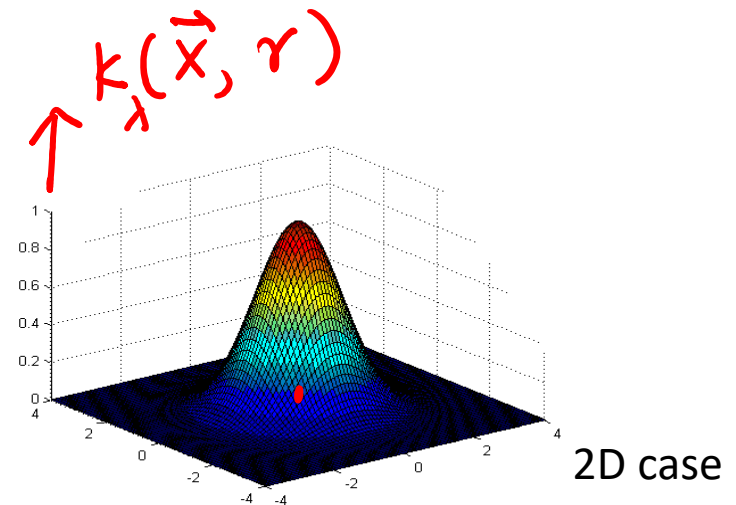
RBF = radial-basis function: a function which depends on the radial distance from a Centre point

Gaussian RBF  $\rightarrow$  
$$K_{\lambda}(x,r) = \exp\left(-\frac{(x-r)^2}{2\lambda^2}\right)$$

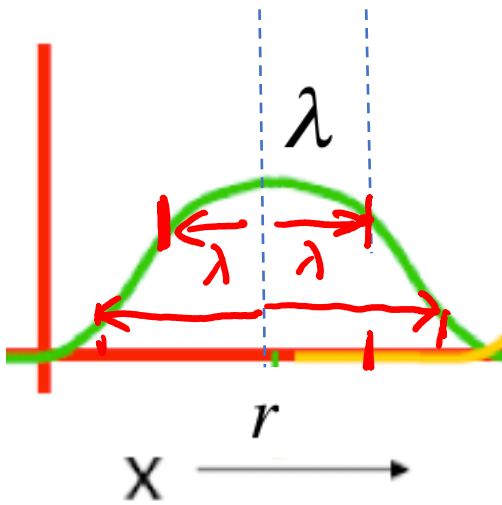
as distance from the center  $r$  increases, the output of the RBF decreases



1D case



2D case



$$K_{\lambda}(x, r) = \exp\left(-\frac{(x-r)^2}{2\lambda^2}\right)$$

↓  
 $\gamma$

$X =$	$K_{\lambda}(x, r) =$
$r$	$1$
$r + \lambda$	<u>0.6065307</u>
$r + 2\lambda$	0.1353353
$r + 3\lambda$	0.0001234098 <span style="color: red;">~ 0</span>

0

$\left\{ \begin{array}{l} X > \gamma + 3\lambda \\ X < \gamma - 3\lambda \end{array} \right.$

# LR with radial-basis functions

- E.g.: LR with RBF regression:

$$\hat{y} = \theta_0 + \sum_{j=1}^m \theta_j \varphi_j(x) = \varphi(x)^T \theta$$

$$\varphi_j(x) := K_{\lambda_j}(x, r_j) = \exp\left(-\frac{(x - r_j)^2}{2\lambda_j^2}\right)$$

*(Handwritten red annotations: a bracket under  $r_j$  and  $\lambda_j$  in the kernel function, and a red  $r_j$  in the exponent)*

hyperparameters of RBF basis functions  
(the predefined Centers and Width)

# LR with radial-basis functions

- E.g.: LR with RBF regression:

$$\hat{y} = \theta_0 + \sum_{j=1}^m \theta_j \varphi_j(x) = \varphi(x)^T \theta$$

$$\varphi_j(x) := \underbrace{K}_{\lambda_j}(x, \underbrace{r}_j) = \exp\left(-\frac{(x - \mu_j)^2}{2\lambda_j^2}\right)$$

$\varphi(x)$ : E.g. with four predefined RBF kernels

$$= \left[1, K_{\lambda_1}(x, r_1), K_{\lambda_2}(x, r_2), K_{\lambda_3}(x, r_3), K_{\lambda_4}(x, r_4)\right]^T$$



e.g. (2) LR with radial-basis functions

- E.g.: LR with RBF regression:

$$\hat{y} = \theta_0 + \sum_{j=1}^m \theta_j \varphi_j(x) = \varphi(x)^T \theta$$

$$\varphi(x) := \left[ \underset{\text{bias}}{1}, K_{\lambda_1}(x, r_1), K_{\lambda_2}(x, r_2), \underset{\text{weights}}{K_{\lambda_3}(x, r_3)}, K_{\lambda_4}(x, r_4) \right]^T$$

$$\vec{\theta} = \left[ \theta_0, \theta_1, \theta_2, \theta_3, \theta_4 \right]^T$$

$\theta_1$   $r_1$   $\theta_2$   $r_2$   $\theta_3$   $\lambda_3$   $\theta_4$   $r_4$  } hyper para  
 $\lambda_1$   $\lambda_2$   $r_3$   $\lambda_4$

$$\theta_{\lambda_i}^* = (\varphi^T \varphi)^{-1} \varphi^T \bar{y}$$

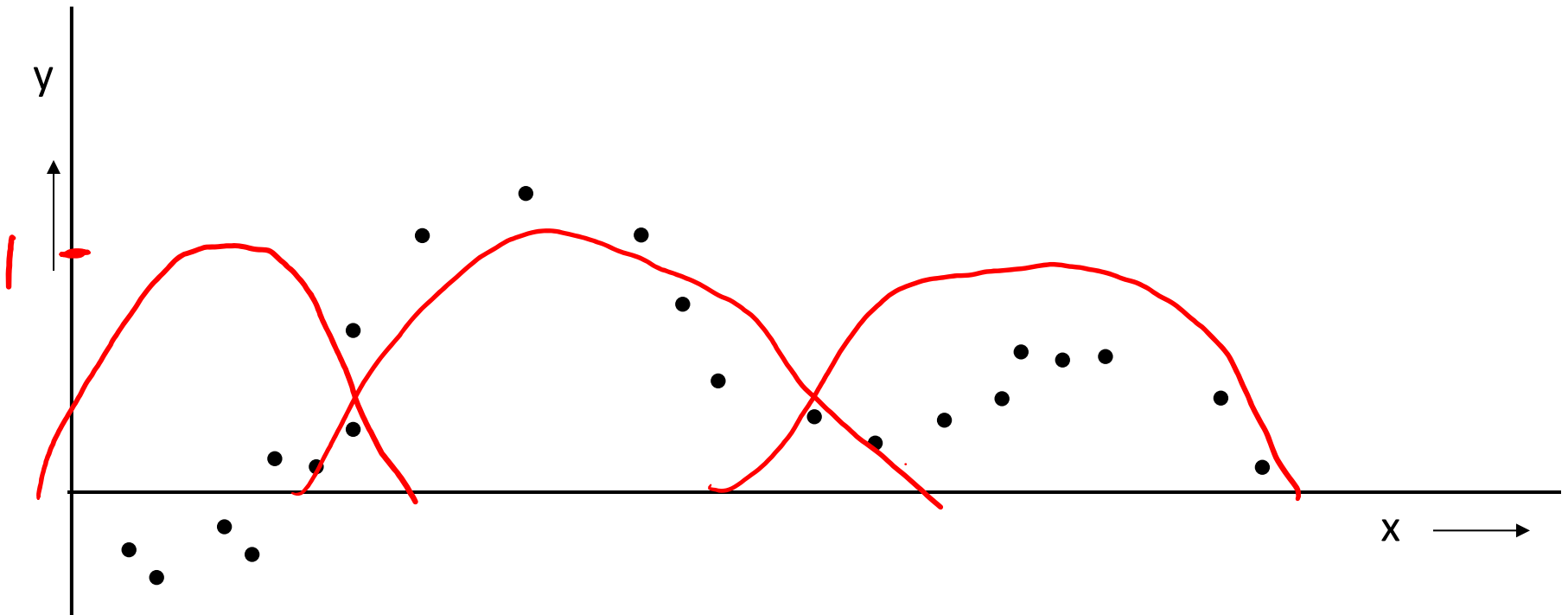
Users need to define the **hyperparameters** of RBF basis functions (the **predefined Centers and Width**)

$\varphi(x)$ : E.g. **with four predefined RBF kernels**

$$= \left[ 1, K_{\lambda_1}(x, r_1), K_{\lambda_2}(x, r_2), K_{\lambda_3}(x, r_3), K_{\lambda_4}(x, r_4) \right]^T$$

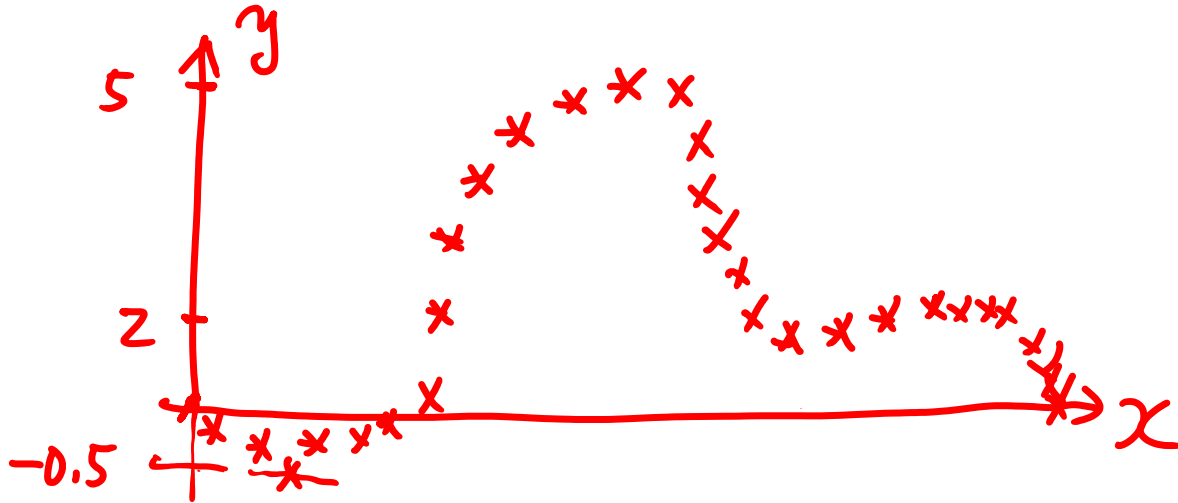
$$\theta^* = \left( \underline{\varphi^T \varphi} \right)^{-1} \varphi^T \bar{y}$$

For example: I want to using 3 RBF basis functions to fit the following data points  
(I need to assume 3 predefined centres and width)



Given Training Data's scatter plot:

$$(x_i, y_i) \quad i=1, \dots, n$$



After my 3 RBF fit:

$$f(x) = \theta_0 - 0.5 k_{\lambda_1}(x, \underline{r_1}) + 5 k_{\lambda_2}(x, \underline{r_2}) + 2 k_{\lambda_3}(x, \underline{r_3})$$

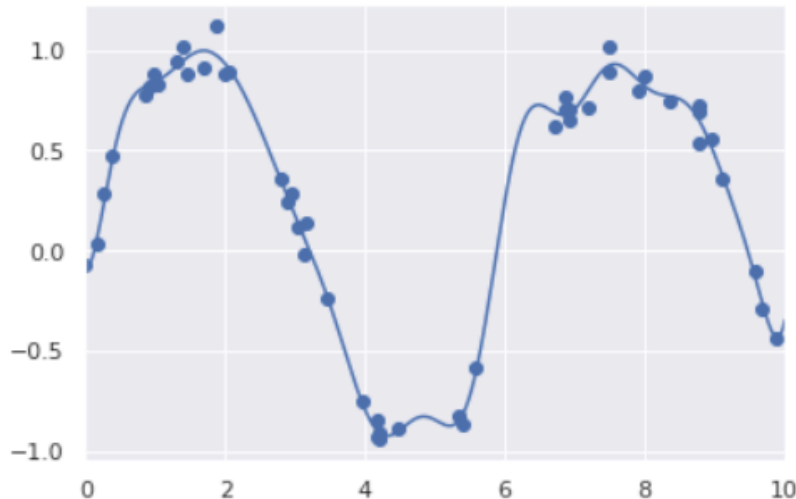
<https://colab.research.google.com/drive/1BVcHUBYDO4AlwldcKmpmj5blAbf7ISJb?usp=sharing>

Modified from:

<https://jakevdp.github.io/PythonDataScienceHandbook/05.06-linear-regression.html>

```
gauss_model = make_pipeline(GaussianFeatures(20),
                             LinearRegression())
gauss_model.fit(x[:, np.newaxis], y)
yfit = gauss_model.predict(xfit[:, np.newaxis])

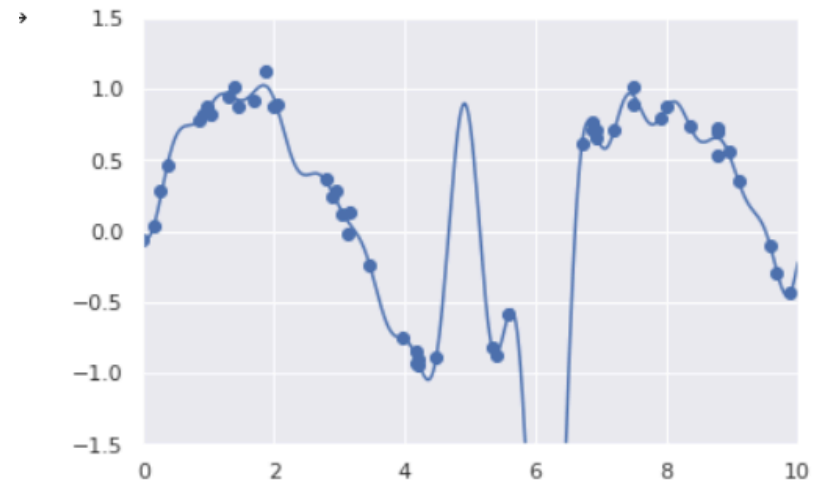
plt.scatter(x, y)
plt.plot(xfit, yfit)
plt.xlim(0, 10);
```



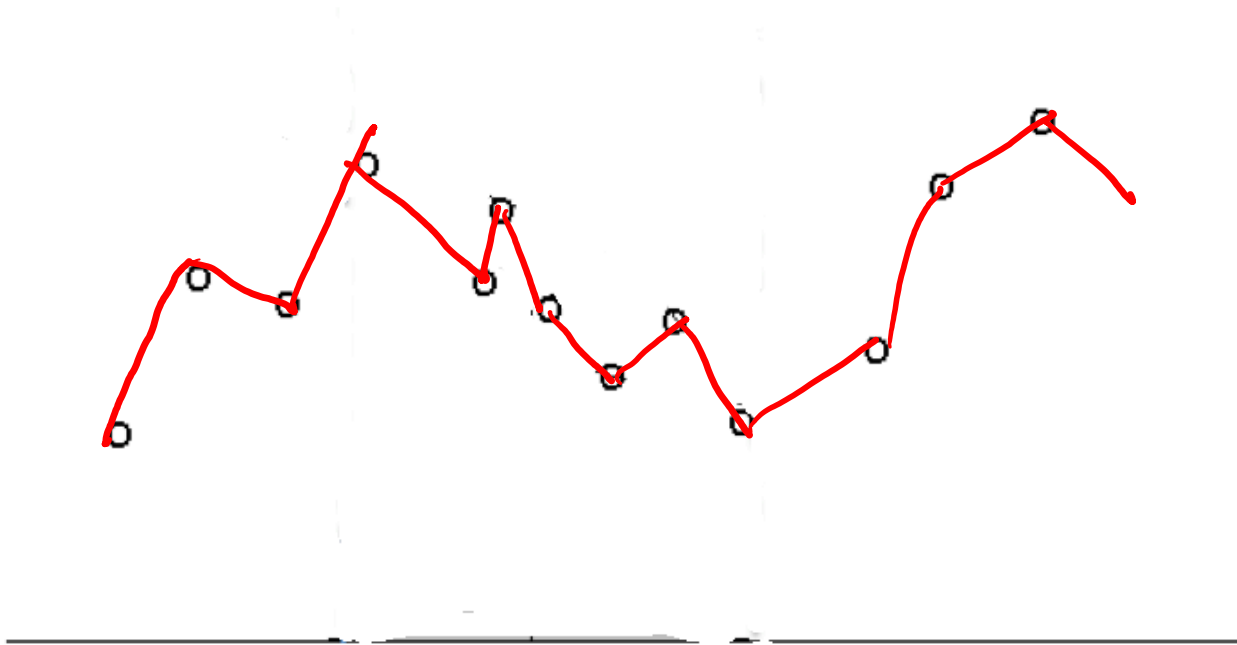
```
model = make_pipeline(GaussianFeatures(30),
                       LinearRegression())
model.fit(x[:, np.newaxis], y)

plt.scatter(x, y)
plt.plot(xfit, model.predict(xfit[:, np.newaxis]))

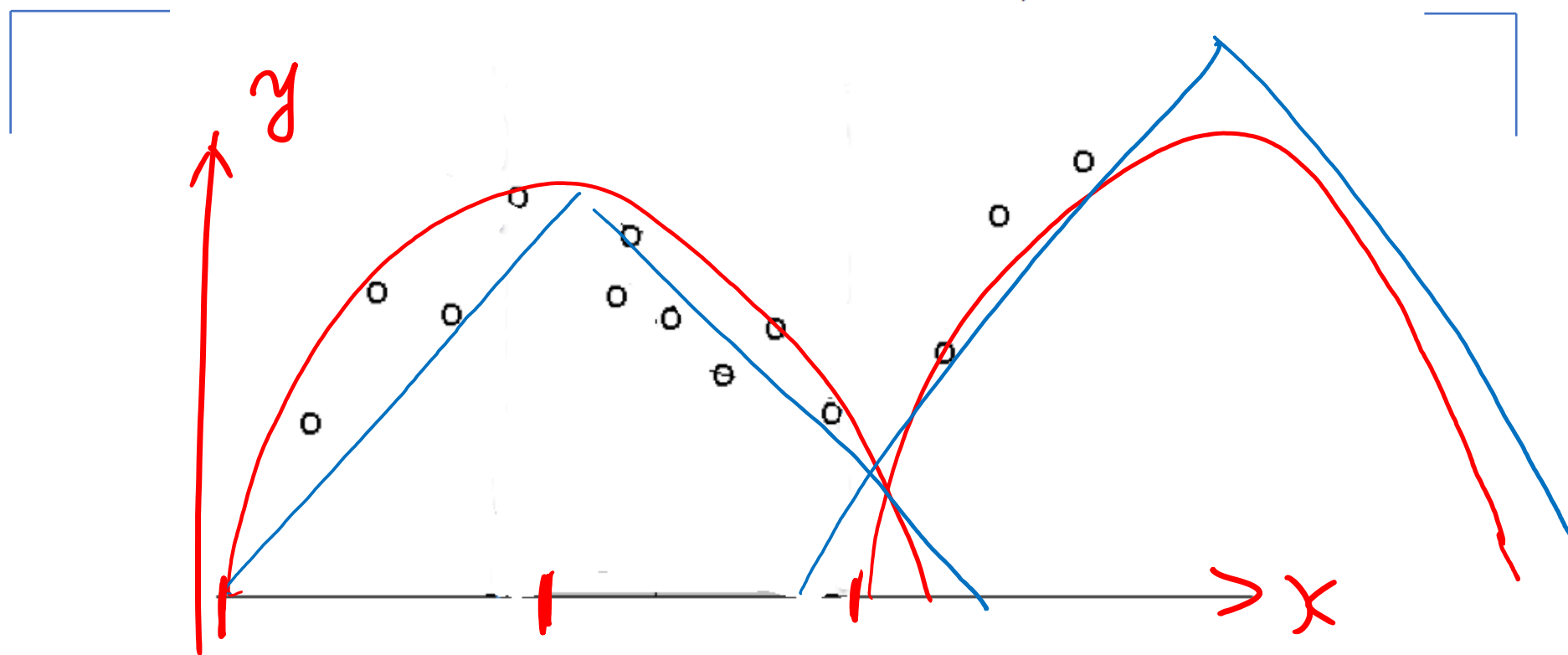
plt.xlim(0, 10)
plt.ylim(-1.5, 1.5);
```



Extra: even more possible Basis Function:  
RBF, or **Piecewise Linear** based?



e.g. Even more possible Basis Func?



# Thank You







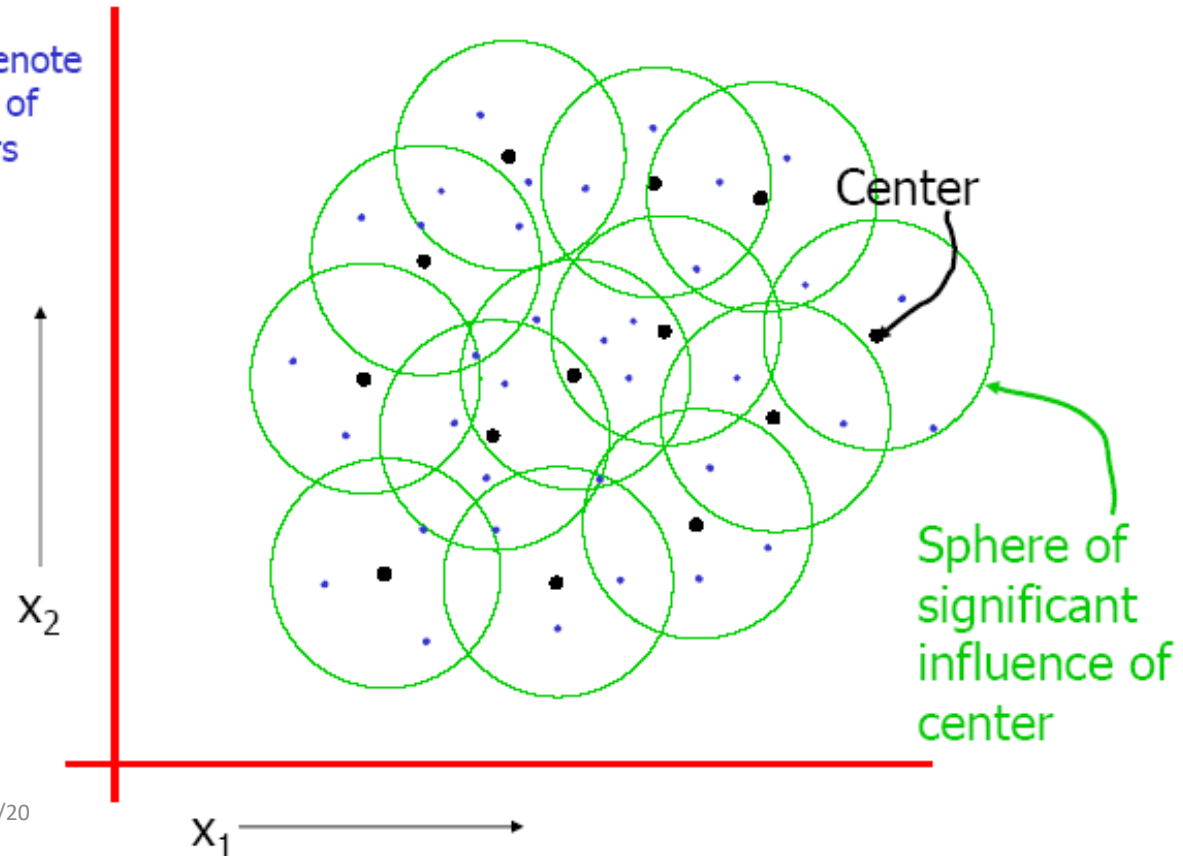
# Extra

# Extra: e.g. 2D Good and Bad RBF Basis

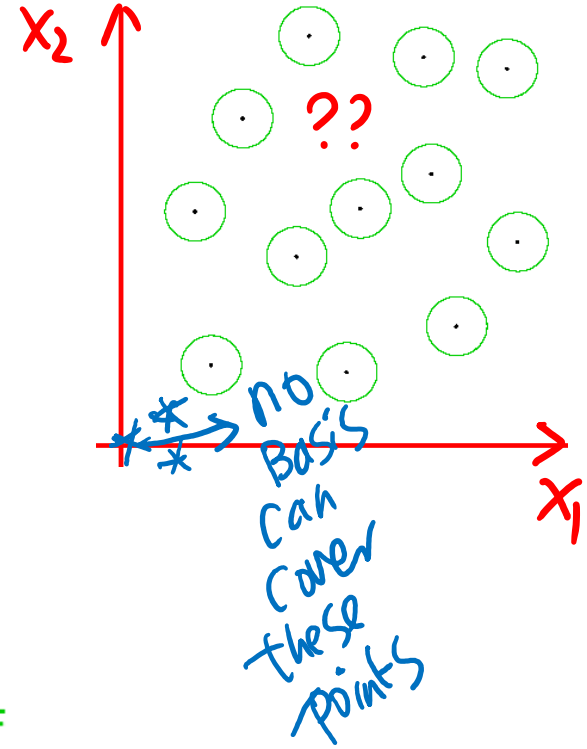
*Contour view*

- A good set of 2D predefined RBF basis

Blue dots denote coordinates of input vectors



- A Bad set of predefined 2D RBFs



# Extra: Nonparametric Regression Models

- K-Nearest Neighbor (KNN) and Locally weighted linear regression are **non-parametric** algorithms.
- The (unweighted) linear regression algorithm that we saw earlier is known as a **parametric** learning algorithm
  - because it has a fixed, finite number of parameters which are fit to the data;
  - Once we've fit the  $\theta$  and stored them away, we no longer need to keep the training data around to make future predictions.
  - In contrast, to make predictions using KNN or locally weighted linear regression, we need to keep the entire training set around.
- The term "**non-parametric**" (roughly) refers to the fact that the amount of knowledge we need to keep, in order to represent the hypothesis grows with linearly the size of the training set.