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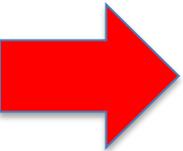
UVA CS 4774: Machine Learning

S3 : Lecture 15: Probability Review

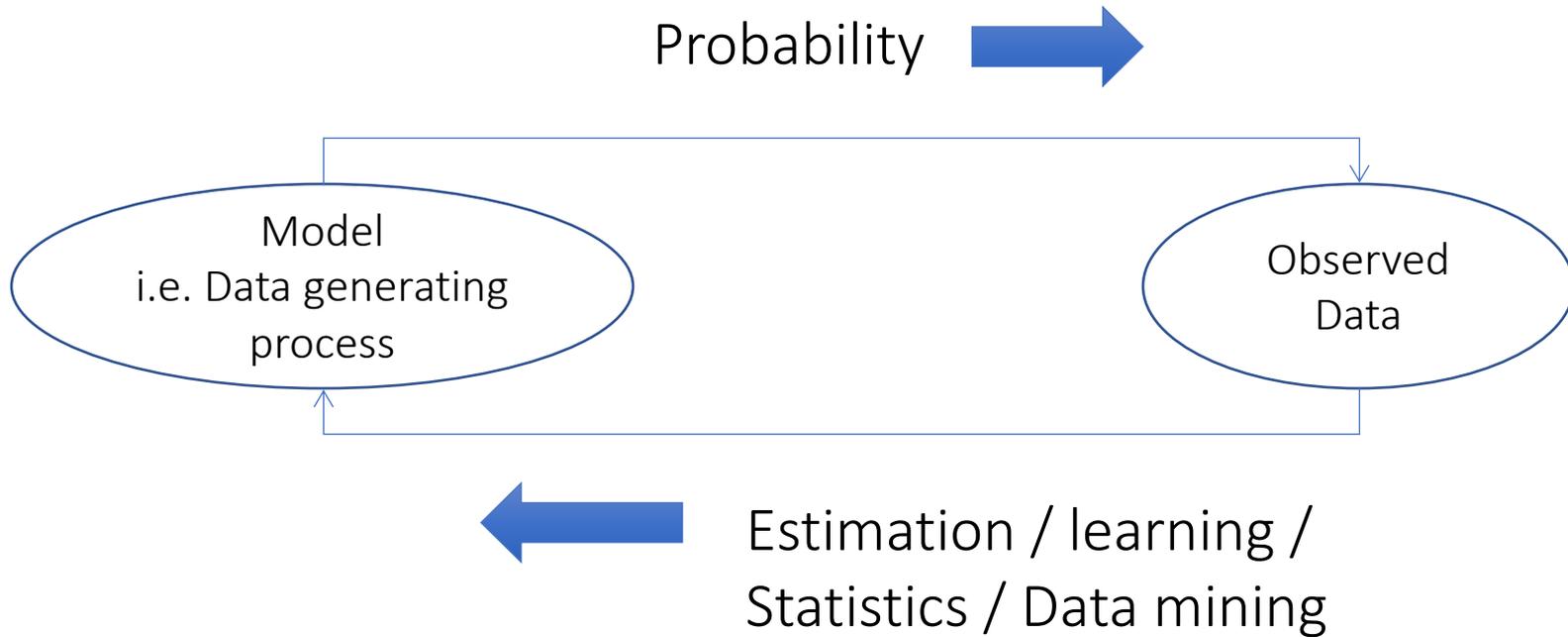
Dr. Yanjun Qi

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Today : Probability Review

- 
- The big picture
 - Events and Event spaces
 - Random variables
 - Joint probability, Marginalization, conditioning, chain rule, Bayes Rule, law of total probability, etc.
 - Structural properties, e.g., Independence, conditional independence
 - Maximum Likelihood Estimation

The Big Picture



Probability

- Counting
- Basics of probability
- Conditional probability
- Random variables
- Discrete and continuous distributions
- Expectation and variance
- Tail bounds and central limit theorem
-

Statistics

- Maximum likelihood estimation
- Bayesian estimation
- Hypothesis testing
- Linear regression
- [Machine learning]
-

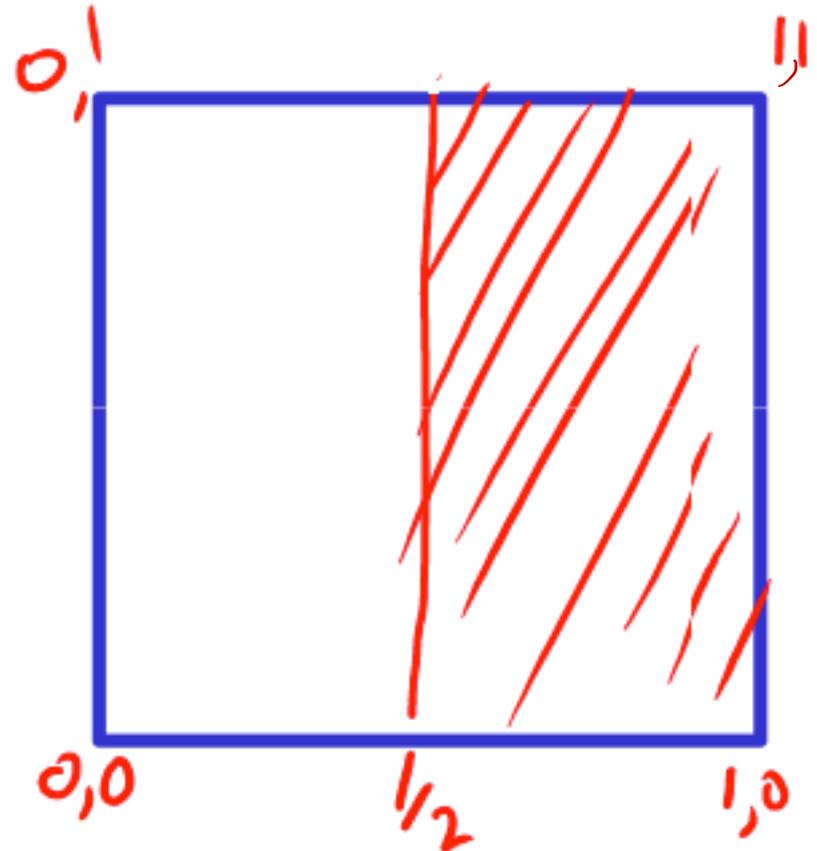
Probability as frequency

- Consider the following questions:
 - 1. What is the probability that when I flip a coin it is “heads”?
We can count → $\sim 1/2$
 - 2. why ?
 - 3. What is the probability of Blue Ridge Mountains to have an erupting volcano in the near future ?
→ could not count

Message: The **frequentist** view is very useful, but it seems that we can also use **domain knowledge** to come up with probabilities.

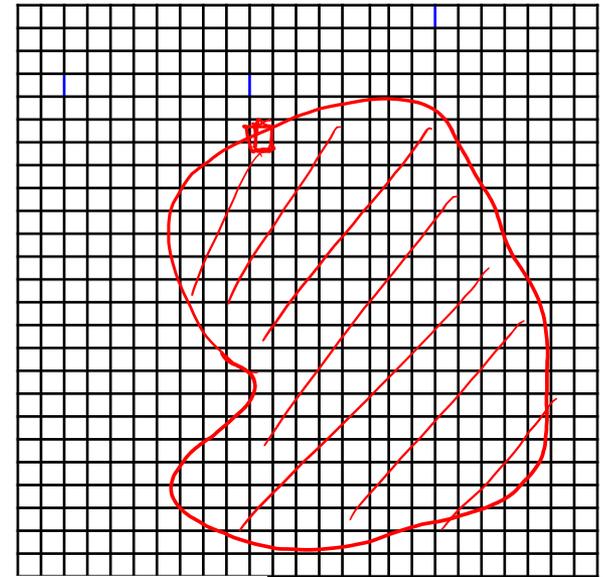
Probability as a measure of uncertainty

- Imagine we are throwing darts at a wall of size 1×1 and that all darts are guaranteed to fall within this 1×1 wall.
- What is the probability that a dart will fall in the shaded area?



Probability as a measure of uncertainty

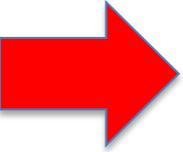
- Probability is a **measure of certainty of an event taking place.**
- i.e. in the example, we were measuring the chances of hitting the shaded area.



Its area is 1 

$$prob = \frac{\# RedBoxes}{\# Boxes}$$

Today : Probability Review

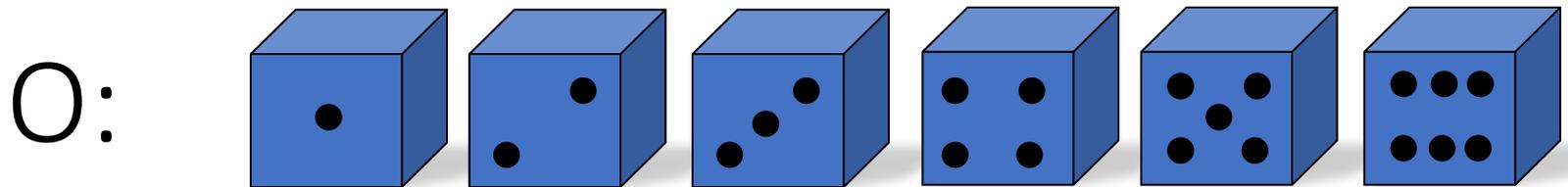
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Probability

Probability is the formal study of the laws of chance. Probability allows us to **manage uncertainty**.

The **sample space** is the set of all **outcomes**. For example, for a die we have 6 outcomes:

$$O_{\text{die}} = \{1, 2, 3, 4, 5, 6\}$$



Elementary Event "Throw 2"

The elements of O are called elementary events.

Probability

- *Probability allows us to measure many **events**.*
- *The events are subsets of the sample space Ω . For example, for a die we may consider the following events: e.g.,*

$$\text{GREATER} = \{5, 6\}$$

$$\text{EVEN} = \{2, 4, 6\}$$

- *Assign probabilities to these events: e.g.,*

$$P(\text{EVEN}) = 1/2$$

Sample space and Events

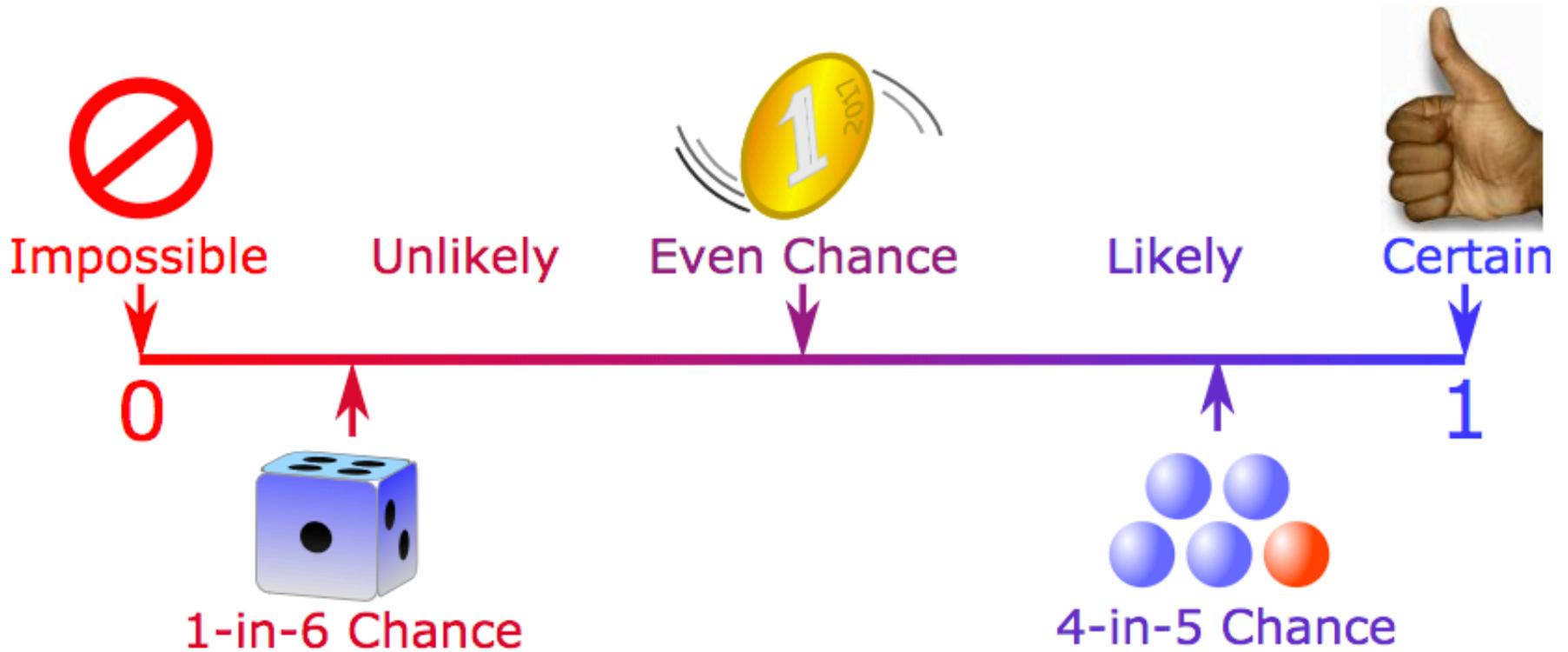
- Ω : **Sample Space**,
 - result of an experiment / set of all outcomes
 - If you toss a coin **twice** $\Omega = \{HH, HT, TH, TT\}$
- **Event**: a subset of Ω
 - First toss is head = $\{HH, HT\}$
- \mathcal{S} : **event space, a set of events**:
 - Contains the empty event and Ω

Axioms for Probability

Sample Space

Event Space

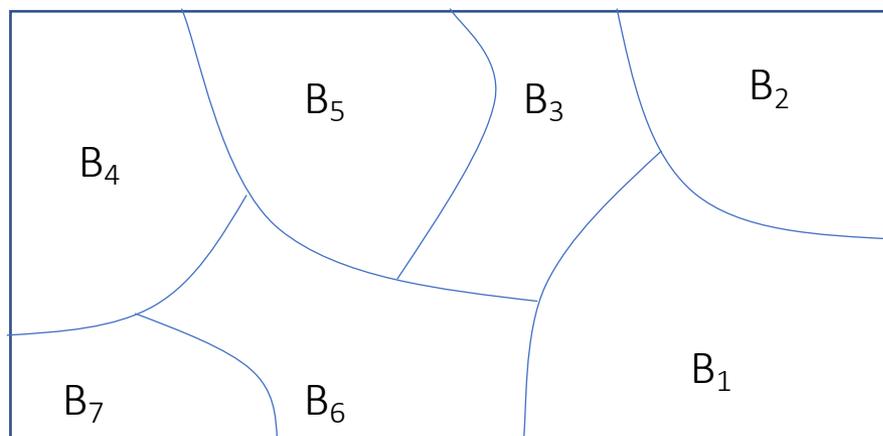
- Defined over (Ω, \mathcal{F}) s.t.
 - $1 \geq P(A) \geq 0$ for all A in \mathcal{F}
 - $P(\Omega) = 1$
 - If A, B are **disjoint**, then
 - $P(A \cup B) = P(A) + P(B)$



Probability is always between 0 and 1

Axioms for Probability

$$\bullet P(\Omega) = \sum P(B_i) = 1$$

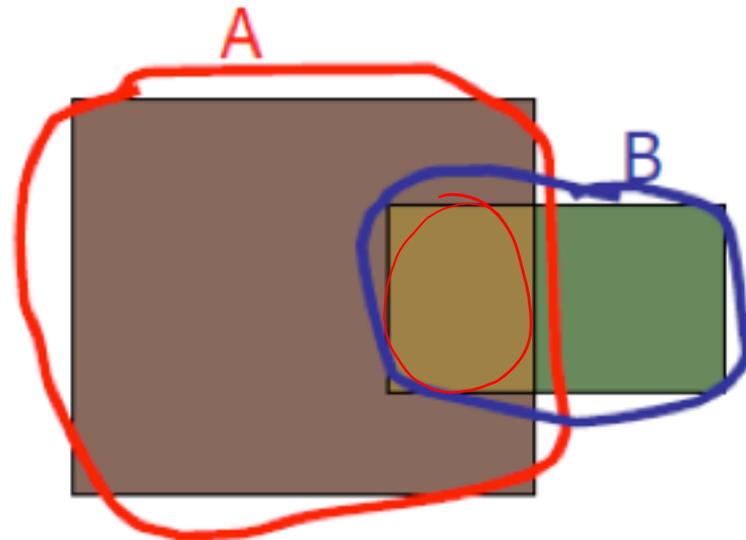


OR operation for Probability

- We can deduce other axioms from the above ones
 - Ex: $P(A \cup B)$ for **non-disjoint** events

$$P(A \text{ or } B) = P(A) + P(B) - P(A \text{ and } B)$$

P(Union of A set and B set)

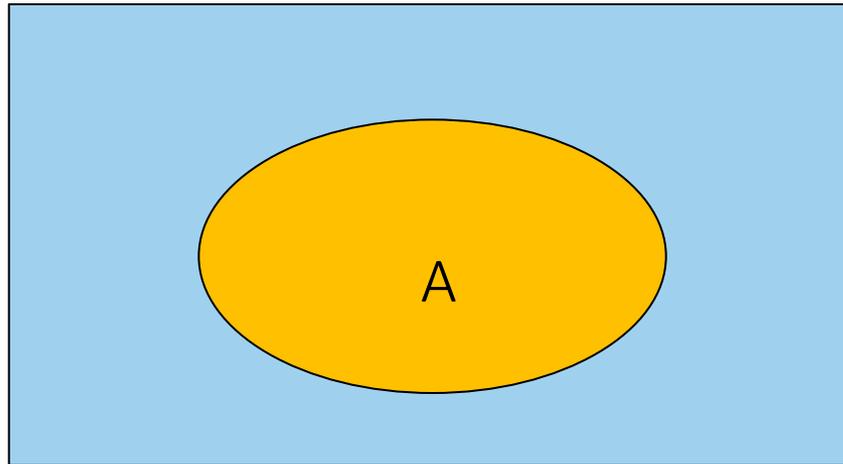


NOT operation for Probability

- $0 \leq P(A) \leq 1$,
- $P(A \text{ or } B) = P(A) + P(B) - P(A \text{ and } B)$

From these we can prove:

$$P(\text{not } A) = P(\sim A) = 1 - P(A)$$



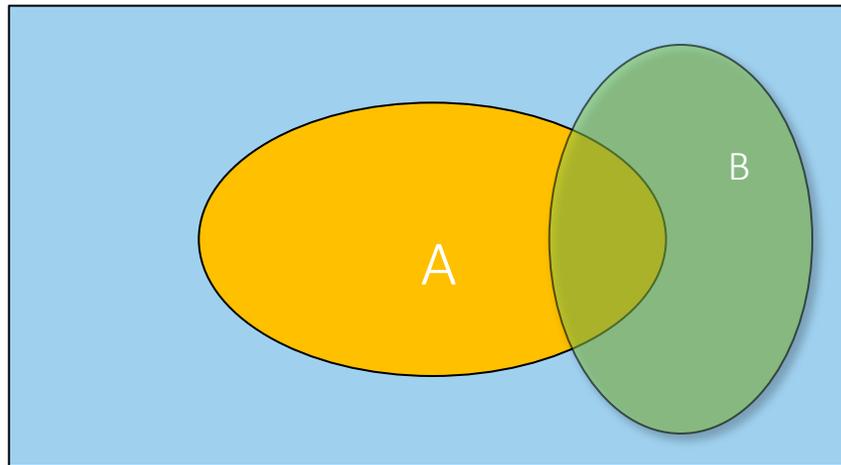
Law of Total Probability

- $0 \leq P(A) \leq 1$,
- $P(A \text{ or } B) = P(A) + P(B) - P(A \text{ and } B)$

From these we can prove:

$$P(A) = P(A \wedge B) + P(A \wedge \sim B)$$

P(Intersection of A and B)

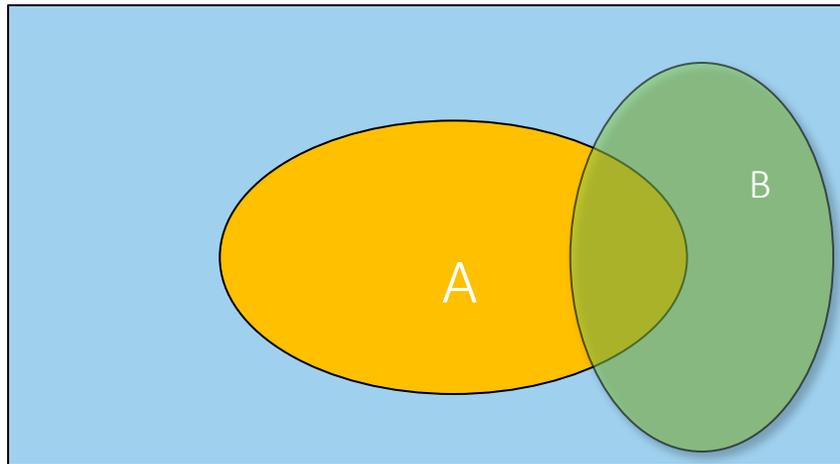


Law of Total Probability

- $0 \leq P(A) \leq 1$,
- $P(A \text{ or } B) = P(A) + P(B) - P(A \text{ and } B)$

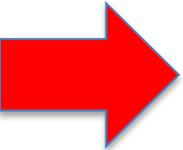
From these we can prove:

$$P(A) = P(A \cap B) + P(A \cap \sim B)$$



$$\begin{aligned} P(A) &= P(A \cap \Omega) \\ &= P(A \cap (B \cup \sim B)) \\ &= P((A \cap B) \cup (A \cap \sim B)) \\ &= P(A \cap B) + P(A \cap \sim B) \end{aligned}$$

Today : Probability Review

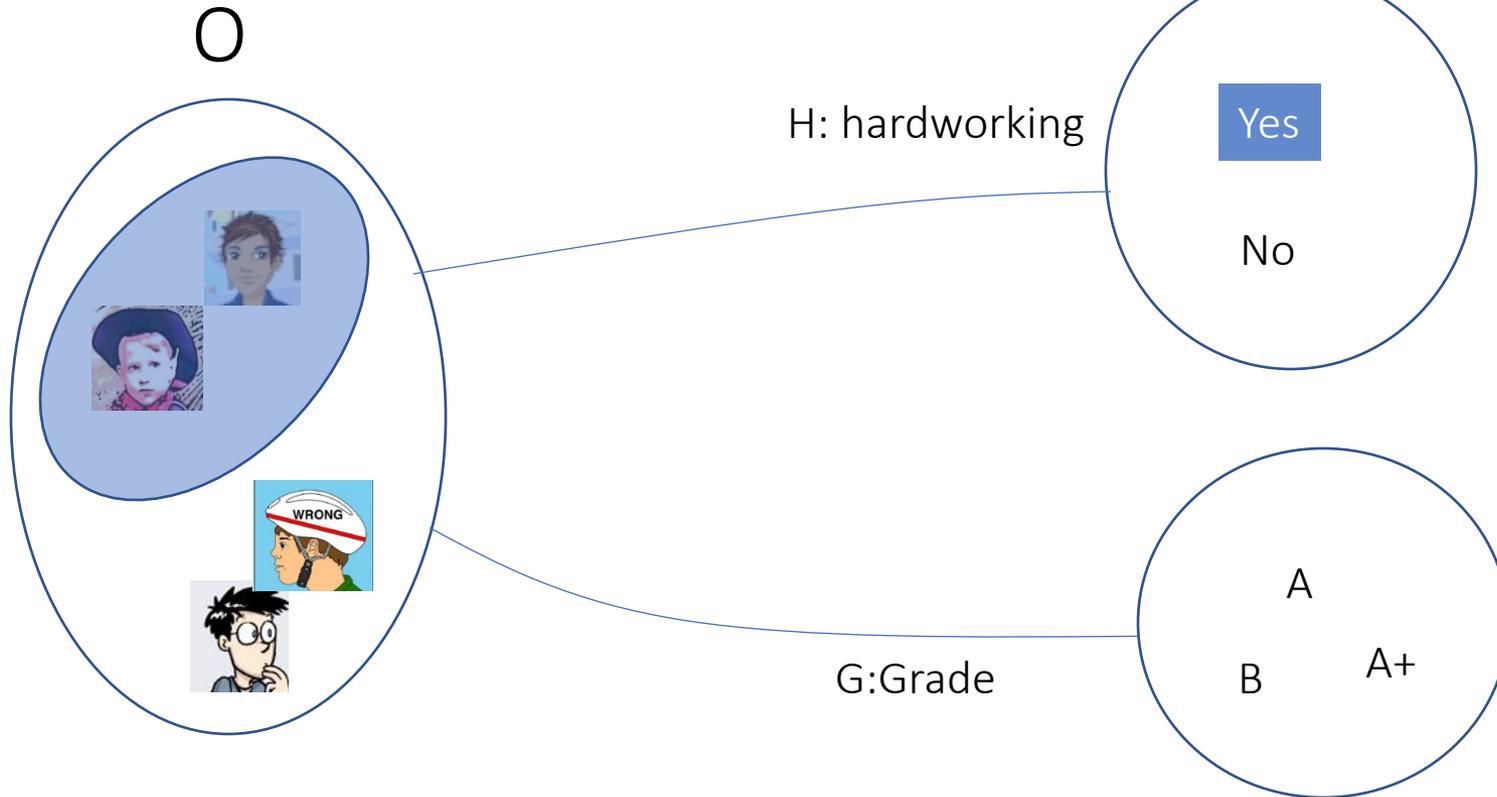
- The big picture
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From Events to Random Variable (RV)

- Concise way of specifying attributes of outcomes
- Modeling students (Grade and Intelligence):
 - O = all possible students (sample space)
 - What are events (subset of sample space)
 - Grade_A = all students with grade A
 - Grade_B = all students with grade B
 - HardWorking_Yes = ... who works hard
 - Very cumbersome
- Need “functions” that maps from O to an attribute space T .
- $P(H = \text{YES}) = P(\{\text{student} \in O : H(\text{student}) = \text{YES}\})$

Random Variables (RV)

$P(H=Yes)$



$P(H = Yes) = P(\{ \text{all students who is working hard on the course} \})$

- “functions” that maps from O to an attribute space T .

Notations

- $P(A)$ is shorthand for $P(A=\text{true})$
- $P(\sim A)$ is shorthand for $P(A=\text{false})$
- Same notation applies to other **binary** RVs:
 $P(\text{Gender}=\text{M})$, $P(\text{Gender}=\text{F})$
- Same notation applies to **multivalued** RVs:
 $P(\text{Major}=\text{history})$, $P(\text{Age}=19)$, $P(Q=c)$
- Note: **upper case letters/names for variables**, **lower case letters/names for values**

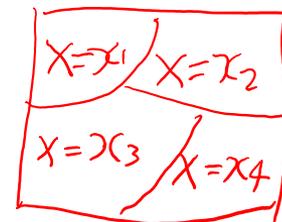
Discrete Random Variables

- Random variables (RVs) which may take on only a countable number of distinct values
- X is a RV with arity k if it can take on exactly one value out of $\{x_1, \dots, x_k\}$

Probability of Discrete RV

- Probability mass function (pmf): $P(X = x_i)$
- Easy facts about pmf
 - $\sum_i P(X = x_i) = 1$
 - $P(X = x_i \cap X = x_j) = 0$ if $i \neq j$
 - $P(X = x_i \cup X = x_j) = P(X = x_i) + P(X = x_j)$ if $i \neq j$
 - $P(X = x_1 \cup X = x_2 \cup \dots \cup X = x_k) = 1$

$$\sum_{i=1}^4 P(X = x_i) = 1$$



e.g. Coin Flips

- You flip a coin
 - Head with probability p , e.g. =0.5

- You flip a coin for k , e.g., =100 times
 - How many heads would you expect

e.g. Coin Flips cont.

- You flip a coin
 - Head with probability p
 - Binary random variable
 - Bernoulli trial with success probability p
- You flip a coin for k times
 - How many heads would you expect
 - Number of heads X is a discrete random variable
 - Binomial distribution with parameters k and p

$$\text{Binary} = \{H, T\}$$

$$p(\# \text{Heads})$$

$$\text{Integer } \{1, 2, \dots, k\}$$

Discrete Random Variables

- Random variables (RVs) which may take on only a **countable** number of **distinct** values
 - E.g. the total number of heads X you get if you flip 100 coins
- X is a RV with arity k if it can take on exactly one value out of
 - E.g. the possible values that X can take on are 0, 1, 2, ..., 100

$$\{x_1, \dots, x_k\}$$

e.g., two Common Distributions

- Uniform

- X takes values 1, 2, ..., N

$$X \sim U[1, \dots, N]$$

- E.g. picking balls of different colors from a box

$$P(X = i) = 1/N$$

- Binomial

- X takes values 0, 1, ..., k

$$X \sim \text{Bin}(k, p)$$

- E.g. coin flips k times

$$P(X = i) = \binom{k}{i} p^i (1-p)^{k-i}$$

↓
~ heads out k

UVA CS 4774: Machine Learning

S3 : Lecture 15: Probability Review

Module II

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- Joint probability, Marginalization, conditioning, chain rule, Bayes Rule, law of total probability, etc.
- Structural properties
 - Independence, conditional independence

If hard to directly estimate from data, most likely we can estimate

- 1. Joint probability
 - Use Chain Rule

$$P(A, B) = P(B) P(A|B)$$

- 2. Marginal probability
 - Use the total law of probability

$$P(B) = P(B, A) + P(B, \sim A)$$
$$\parallel$$
$$P(B, A \cup \sim A) \parallel$$

- 3. Conditional probability
 - Use the Bayes Rule

$$P(A|B)$$
$$P(B|A) = \frac{P(A, B)}{P(A)} = \frac{P(A|B) P(B)}{P(A)}$$

(1). To calculate Joint Probability: Use Chain Rule

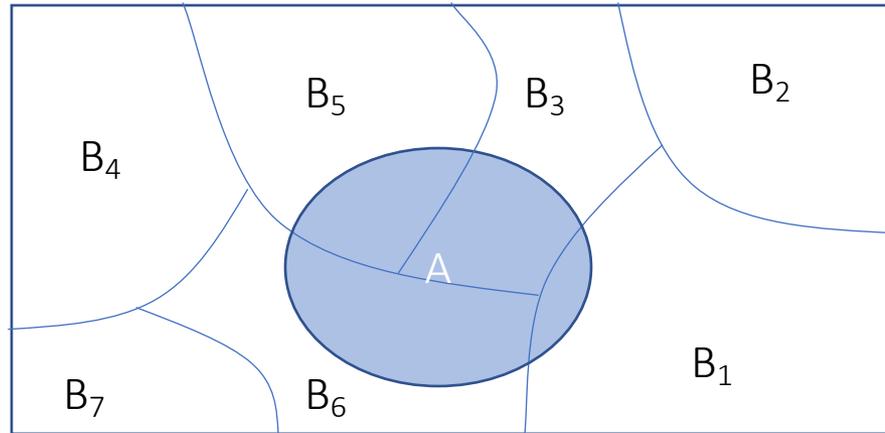
- Two ways to use chain rules on joint probability

$$P(A,B) = p(B|A)p(A) \rightarrow \text{marginal}$$

joint *conditional*

$$P(A,B) = p(A|B)p(B)$$

(2). To calculate Marginal Probability:
 Use Rule of total probability (e.g. event version)



$$P(A) = P(A \cap B) + P(A \cap \sim B)$$

$$\Rightarrow P(A) = \sum P(B_i) P(A|B_i)$$

WHY ???

$$\begin{aligned}
 P(A) &= P(A \cap \Omega) \\
 &= P(A \cap (B_1 \cup B_2 \dots \cup B_k)) \\
 &= \sum P(A \cap B_i)
 \end{aligned}$$

(2). To calculate **Marginal Probability**:
Use Rule of total probability (e.g. RV version)

- Given two discrete RVs X and Y, which take values in:

$$\{x_1, \dots, x_k\} \quad \{y_1, \dots, y_m\}$$

$$\begin{aligned} P(X = x_i) &= \sum_j P(X = x_i \cap Y = y_j) \\ &= \sum_j P(X = x_i | Y = y_j) P(Y = y_j) \end{aligned}$$



$$P(A) = P(A \wedge B) + P(A \wedge \sim B)$$

(3). To calculate **Conditional Probability**:
Use Bayes Rule (e.g. RV version)

$$P(X = x | Y = y) = \frac{P(X = x \cap Y = y)}{P(Y = y)}$$

One Example

Assume we have a dark box with 3 red balls and 1 blue ball. That is, we have the set $\{r, r, r, b\}$. What is the probability of drawing 2 red balls in the first 2 tries?

$$P(B_1 = r, B_2 = r) =$$

$$P(B_2 = r)$$

$$P(B_1 = r | B_2 = r)$$

One Example: Joint

Assume we have a dark box with 3 red balls and 1 blue ball. That is, we have the set $\{r, r, r, b\}$. What is the probability of drawing 2 red balls in the first 2 tries?

$$P(B_1 = r, B_2 = r) =$$

One Example: Joint

Assume we have a dark box with 3 red balls and 1 blue ball. That is, we have the set $\{r, r, r, b\}$. What is the probability of drawing 2 red balls in the first 2 tries?

$$P(B_1 = r, B_2 = r) = P(B_1 = r) \underbrace{P(B_2 = r \mid B_1 = r)}_{\frac{2}{3}}$$
$$P(B_1 = r) = \frac{3}{4}$$
$$P(B_1 = b) = \frac{1}{4}$$

One Example: Joint

Assume we have a dark box with 3 red balls and 1 blue ball. That is, we have the set $\{r, r, r, b\}$. What is the probability of drawing 2 red balls in the first 2 tries?

$$\begin{aligned} P(B_1 = r, B_2 = r) &= P(B_1 = r) P(B_2 = r | B_1 = r) \\ &= \frac{3}{4} \times \frac{2}{3} = \frac{1}{2} \end{aligned}$$

One Example: Marginal

What is the probability that the 2nd ball drawn from the set $\{r,r,r,b\}$ will be red?

Using marginalization, $P(B_2 = r) = P(B_2 = r, B_1 = r) + P(B_2 = r, B_1 = b)$

One Example: Marginal

What is the probability that the 2nd ball drawn from the set $\{r, r, r, b\}$ will be red?

$$\begin{aligned} \text{Using marginalization, } P(B_2 = r) &= P(B_2 = r \wedge B_1 = r) \\ &\quad + P(B_2 = r \wedge B_1 = b) \\ &= P(B_1 = r) P(B_2 = r | B_1 = r) + P(B_1 = b) P(B_2 = r | B_1 = b) \\ &= \frac{3}{4} \times \frac{2}{3} + \frac{1}{4} \times 1 \end{aligned}$$

One Example

Assume we have a dark box with 3 red balls and 1 blue ball. That is, we have the set $\{r, r, r, b\}$. What is the probability of drawing 2 red balls in the first 2 tries?

$$P(B_1 = r, B_2 = r) = \underbrace{P(B_1 = r)}_{\frac{3}{4}} P(B_2 = r | B_1 = r) = \frac{1}{2}$$

$$P(B_2 = r) = P(B_1 = r, B_2 = r) + P(B_1 = b, B_2 = r)$$

$$P(B_1 = r | B_2 = r) = \frac{P(B_1 = r, B_2 = r)}{P(B_2 = r)}$$

One Example: Conditional

} Chain Rule
} total law Prob

$$P(B_1=r | B_2=r) = \frac{P(B_2=r | B_1=r) P(B_1=r)}{P(B_2=r)}$$

⇒ last last page

⇓ Last

$$= \frac{P(B_2=r | B_1=r) P(B_1=r)}{P(B_2=r, B_1=r) + P(B_2=r, B_1=b)}$$

Bayes Rule

$$P(B|A) = \frac{P(A \wedge B)}{P(A)} = \frac{P(A|B) P(B)}{P(A)}$$

This is Bayes Rule

Bayes, Thomas (1763) An essay towards solving a problem in the doctrine of chances. *Philosophical Transactions of the Royal Society of London*, **53:370-418**

Handwritten red notes and a portrait of Thomas Bayes:

$\frac{P(Y=yes) P(X|Y=yes)}{P(X)}$

if $P(Y=yes|x) > P(Y=no|x)$

$\frac{P(Y=no) P(X|Y=no)}{P(X)}$

$\Rightarrow \hat{y}=yes$



More General Forms of Bayes Rule

$$P(A|B) = \frac{P(B|A)P(A)}{P(B|A)P(A) + P(B|\sim A)P(\sim A)}$$

$P(B_2=t, B_1=t)$
 $P(B_2=t, B_1=t) +$
 $P(B_2=t, B_1=b)$

$$P(A|B \wedge X) = \frac{P(B|A \wedge X)P(A \wedge X)}{P(B \wedge X)}$$

$$P(A = a_1 | B) = \frac{P(B | A = a_1)P(A = a_1)}{\sum_i P(B | A = a_i)P(A = a_i)}$$

E.g.: Use both Bayes Rule and Marginal

- X and Y are discrete RVs...

$$P(X = x_i | Y = y_j) = \frac{P(X = x_i \cap Y = y_j)}{P(Y = y_j)}$$

$$\{x_1, \dots, x_k\} \downarrow$$

$$P(X = x_i | Y = y_j) = \frac{P(Y = y_j | X = x_i) P(X = x_i)}{\sum_k P(Y = y_j | X = x_k) P(X = x_k)}$$

Simplify Notation: Conditional Probability

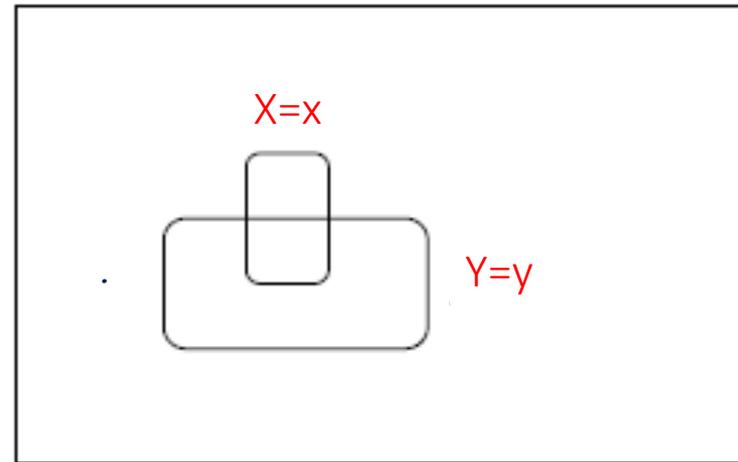
$$P(X = x | Y = y) = \frac{P(X = x \cap Y = y)}{P(Y = y)}$$

events

But we will always write it this way:

$$P(x | y) = \frac{p(x, y)}{p(y)}$$

$P(X=x \text{ true}) \rightarrow P(X=x) \rightarrow P(x)$



$P(x) \leftarrow P(\underline{X}=x) \leftarrow P(\underline{X}(true))$
 value RV event

Simplify Notation:

An Example of estimating conditional

- We know that $P(\text{rain}) = 0.5$
- If we also know that the grass is wet, then how this affects our belief about whether it rains or not?

$$P(\text{rain} \mid \text{wet}) = \frac{P(\text{rain})P(\text{wet} \mid \text{rain})}{P(\text{wet})}$$

W = G =

Simplify Notation:

An Example of estimating conditional

- We know that $P(\text{rain}) = 0.5$
- If we also know that the grass is wet, then how this affects our belief about whether it rains or not?

$$P(\overset{W=}{\text{rain}} \mid \overset{G=}{\text{wet}}) = \frac{P(\text{rain})P(\text{wet} \mid \text{rain})}{P(\text{wet})}$$

$$P(W=S \mid \text{wet})$$

$$P(x \mid y) = \frac{P(x)P(y \mid x)}{P(y)} = \frac{p(x,y)}{p(y)}$$

Simplify Notation: Conditional

- Bayes Rule

$$P(x | y) = \frac{P(x)P(y | x)}{P(y)}$$

- You can condition on **more variables**

$$P(x | y, z) = \frac{P(x | z)P(y | x, z)}{P(y | z)}$$

Simplify Notation: Marginal

- We know $p(X, Y)$, what is $P(Y=y)$ or $P(X=x)$?
- We can use the law of total probability

$$p(x) = \sum_y P(x, y)$$
$$= \sum_y P(y)P(x|y)$$

$\{y_1, \dots, y_m\}$

all possible Y values

$$p(x) = \sum_{y,z} P(x, y, z)$$
$$= \sum_{z,y} P(y, z)P(x|y, z)$$

$\sum_y \sum_z p(y, z) = 1$

Simplify Notation:

An Example

- We know that $P(\text{rain}) = 0.5$
- If we also know that the grass is wet, then how this affects our belief about whether it rains or not?

$$P(\text{rain} \mid \text{wet}) = \frac{P(\text{rain})P(\text{wet} \mid \text{rain})}{P(\text{wet})}$$

Handwritten annotations:

- 0.5 (with an arrow pointing to $P(\text{rain})$)
- $P(\text{wet}, \text{rain})$ (with a line pointing to the numerator)
- $P(\text{wet}, \text{rain}) + P(\text{wet}, \text{sunny})$ (with a line pointing to the denominator)
- $P(\text{rain})P(\text{wet} \mid \text{rain}) + P(\text{sunny})P(\text{wet} \mid \text{sunny})$ (with a line pointing to the denominator)
- $P(\text{wet} \mid \text{sunny})$ (underlined in red)

Labels for variables:

- Weather: {rain, sunny}
- Grass: {wet, dry}

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Independent RVs

- Definition: X and Y are independent *iff*

$$P(X = x \cap Y = y) = P(X = x)P(Y = y)$$

More on Independence

$$P(X = x \cap Y = y) = P(X = x)P(Y = y)$$



$$P(X = x | Y = y) = P(X = x)$$



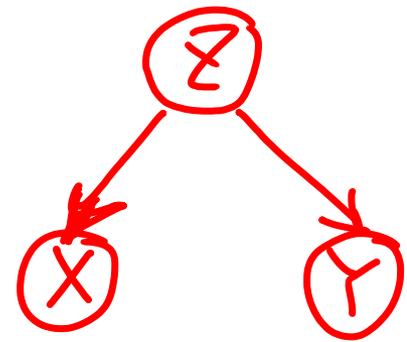
$$P(Y = y | X = x) = P(Y = y)$$

- E.g. no matter how many heads you get, your friend will not be affected, and vice versa

More on Independence

- X is independent of Y means that knowing Y does not change our belief about X .
- The following forms are **equivalent**:
 - $P(X=x, Y=y) = P(X=x) P(Y=y)$
 - $P(X=x | Y=y) = P(X=x)$
- **The above should hold for all x_i, y_j**
- It is symmetric and **written as** $X \perp Y$

Conditionally Independent RVs

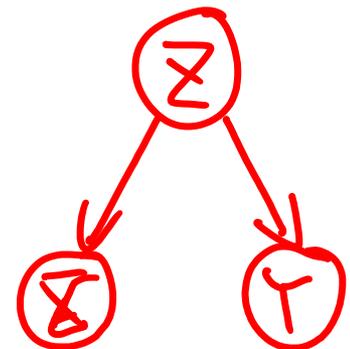


- Intuition: X and Y are conditionally independent given Z means that once Z is **known**, the value of X does not add any **additional** information about Y
- Definition: X and Y are conditionally independent given Z *iff*

$$P(X = x \cap Y = y | Z = z) = P(X = x | Z = z) P(Y = y | Z = z)$$

If holding for all x_i, y_j, z_k

$$X \perp Y | Z$$



More on Conditional Independence

$$P(X = x \cap Y = y | Z = z) = P(X = x | Z = z) P(Y = y | Z = z)$$



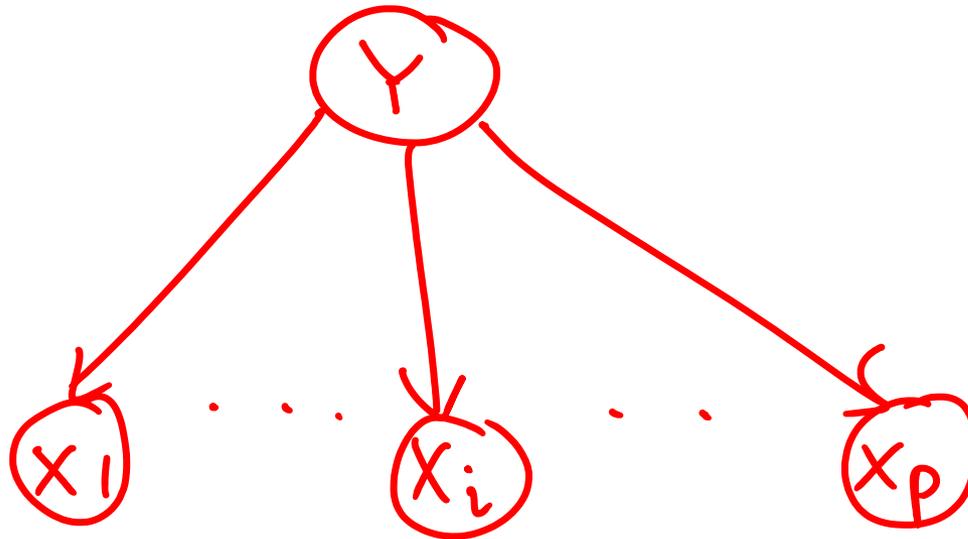
$$P(X = x | Y = y, Z = z) = P(X = x | Z = z)$$



$$P(Y = y | X = x, Z = z) = P(Y = y | Z = z)$$

independence and conditional independence

- Independence does not imply conditional independence.
- Conditional independence does not imply independence.



Today Recap: Probability Review

- The big picture
- Events and Event spaces
- Random variables
- Joint probability, Marginalization, conditioning, chain rule, Bayes Rule, law of total probability, etc.
- Structural properties, e.g., Independence, conditional independence
- Maximum Likelihood Estimation (next class)

References

- Prof. Andrew Moore's review tutorial
- Prof. Nando de Freitas's review slides
- Prof. Carlos Guestrin recitation slides