

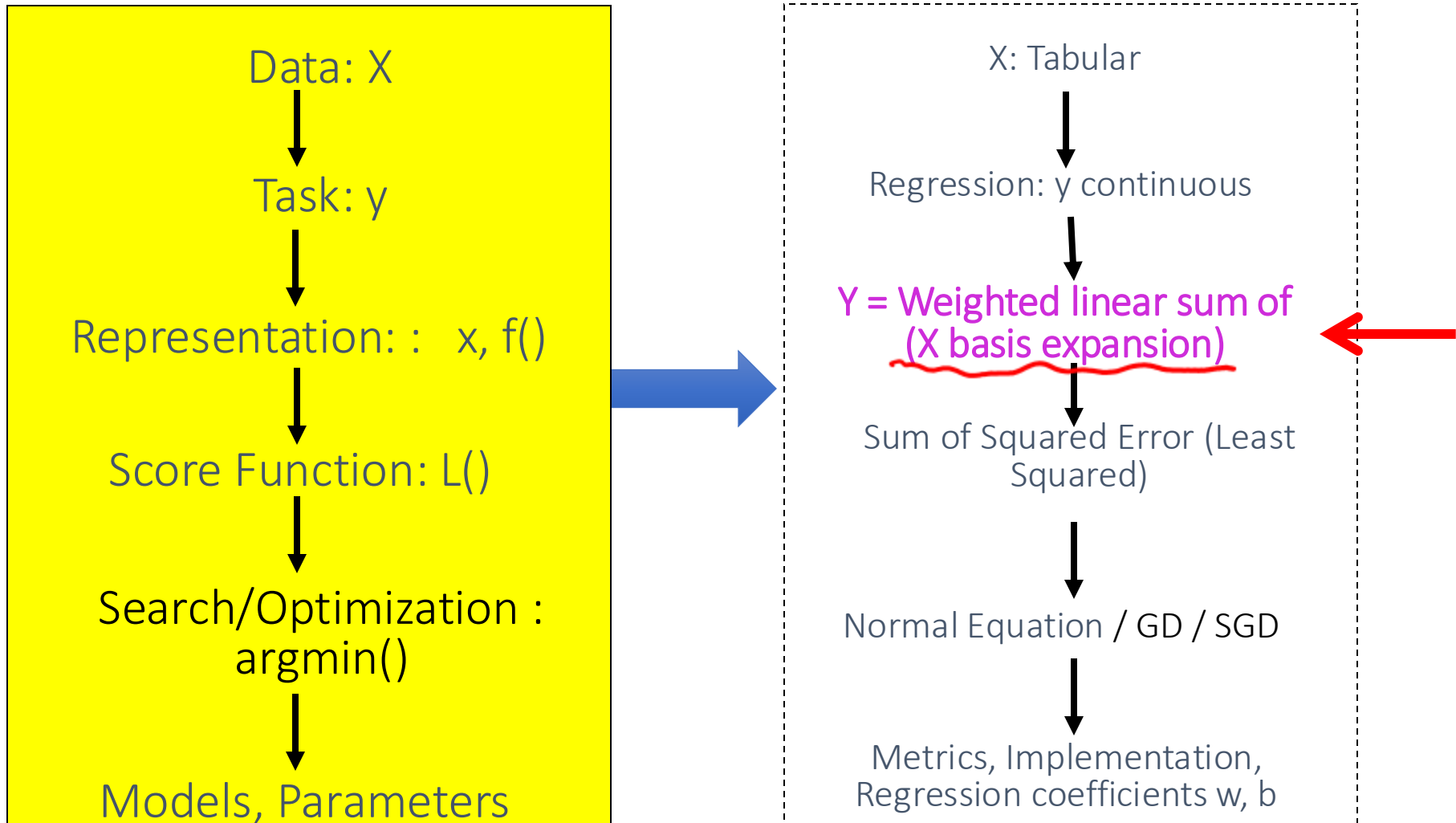
# UVA CS 4774: Machine Learning

## Lecture 5: Linear Regression with Basis Functions Expansion

Dr. Yanjun Qi

University of Virginia  
Department of Computer Science

# Today : Multivariate (non-) Linear Regression with Basis Expansion



$$\hat{y} = \theta_0 + \sum_{j=1}^m \theta_j \varphi_j(x) = \varphi(x)^T \theta$$

# Linear Regression with non-linear basis functions

- LR can deal with nonlinear relationships

$$\hat{y} = \theta^T \mathbf{x} \quad \longrightarrow \quad \hat{y} = \theta_0 + \sum_{j=1}^m \theta_j \varphi_j(\mathbf{x}) = \theta^T \varphi(\mathbf{x})$$

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$$\vec{\theta} = [\theta_0, \theta_1, \dots, \theta_m]^T$$

$$\vec{\Phi} = [1, \varphi_1(x), \dots, \varphi_m(x)]^T$$

# LR with non-linear basis functions

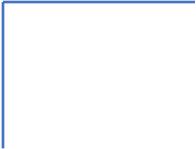
- Free to design basis functions (e.g., non-linear features:

Here  $\varphi_j(x)$  are **[predefined]** basis functions (also  $\varphi_0(x)=1$  )

- E.g.: polynomial regression with degree up-to two (d=2) :

$$\varphi(x) := \begin{bmatrix} 1, x, x^2 \end{bmatrix}^T$$

Linear  $\vec{x} : \begin{bmatrix} 1, x \end{bmatrix}^T$



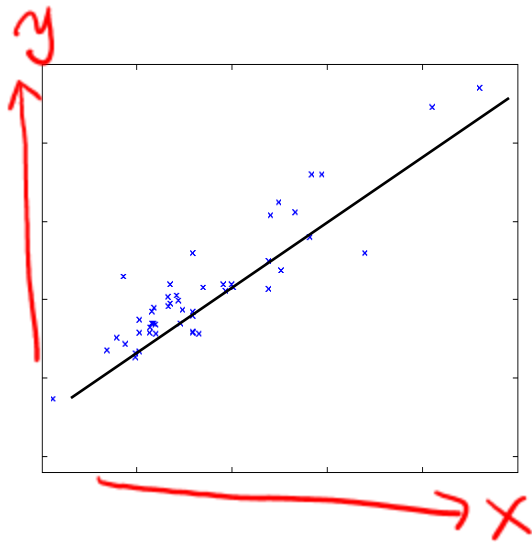
# Polynomial basis based Regression

e.g. (1) polynomial regression

$$\hat{y} = \theta^T \mathbf{x}$$



$$\hat{y} = \theta^T \varphi(\mathbf{x})$$

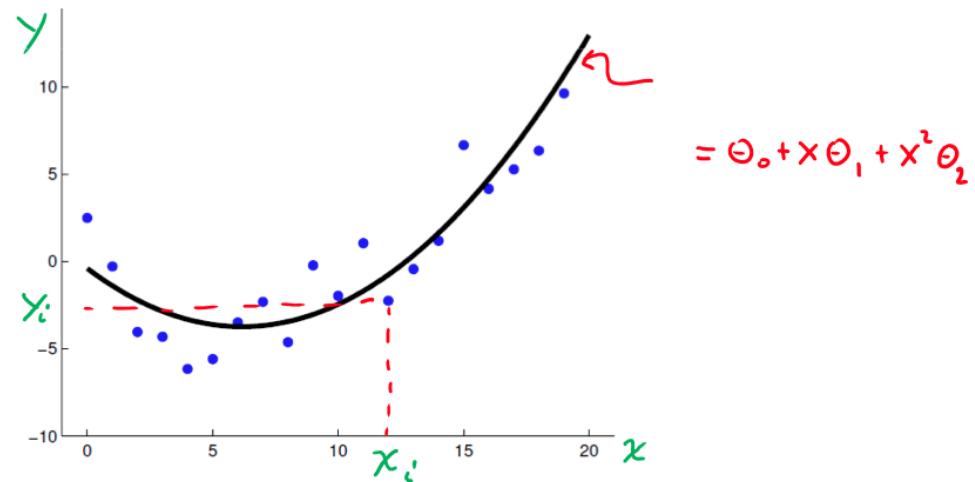
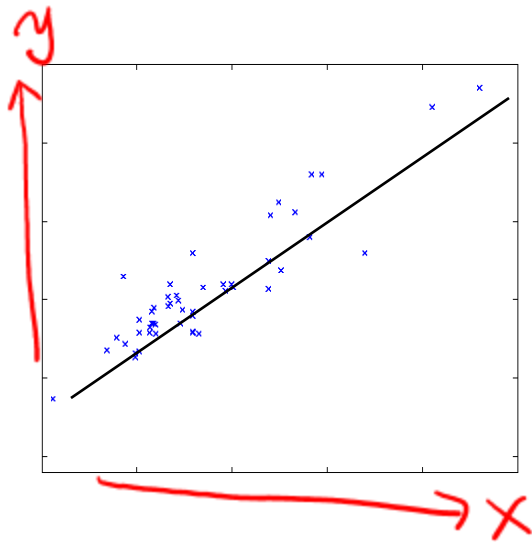


e.g. (1) polynomial regression

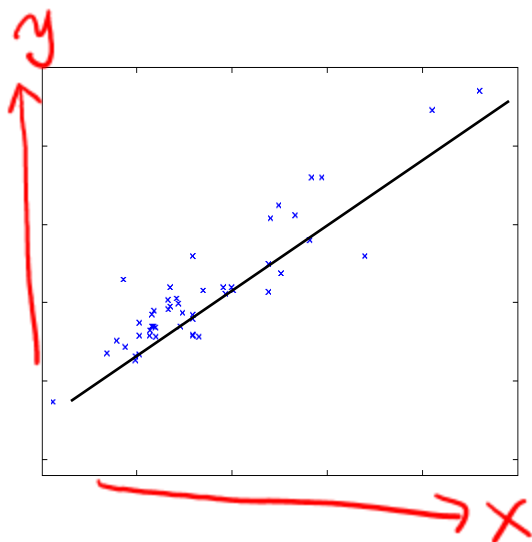
$$\hat{y} = \theta^T \mathbf{x}$$



$$\hat{y} = \theta^T \varphi(\mathbf{x})$$

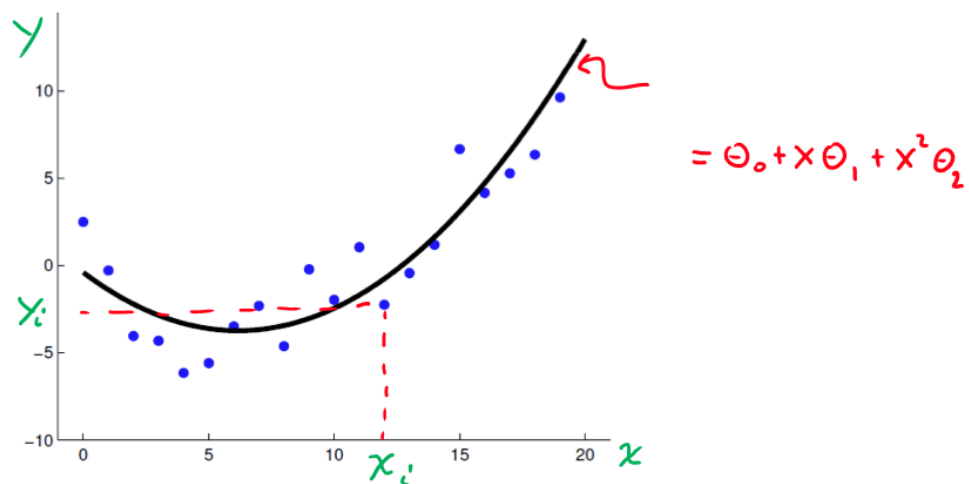


$$\hat{y} = \theta^T \mathbf{x}$$



$$\theta^* = (X^T X)^{-1} X^T \bar{y}$$

$$\hat{y} = \theta^T \varphi(\mathbf{x})$$



$$\theta^* = (\varphi^T \varphi)^{-1} \varphi^T \bar{y}$$

$$\varphi(x) := \begin{bmatrix} 1, x, x^2 \end{bmatrix}^T$$

feature engineering

Linear  $\vec{X} := [1, x]^T$

$$\theta^* = (X^T X)^{-1} X^T \bar{y}$$

$$\Sigma_{n \times p} = \begin{bmatrix} 1 \\ 2 \\ \vdots \\ n \end{bmatrix} \xrightarrow{p+1}$$

p=1

$$\varphi(x) := \begin{bmatrix} 1, x, x^2 \end{bmatrix}^T$$

1   2   ...   m

$$\theta^* = \left( \underbrace{\varphi^T \varphi}_{m \times n \quad n \times n} \right)^{-1} \underbrace{\varphi^T \bar{y}}_{n \times n \quad n \times 1} \quad n \times 1$$

$$\Phi(x) = \begin{bmatrix} 1 \\ 2 \\ 3 \\ \vdots \\ n \end{bmatrix}$$

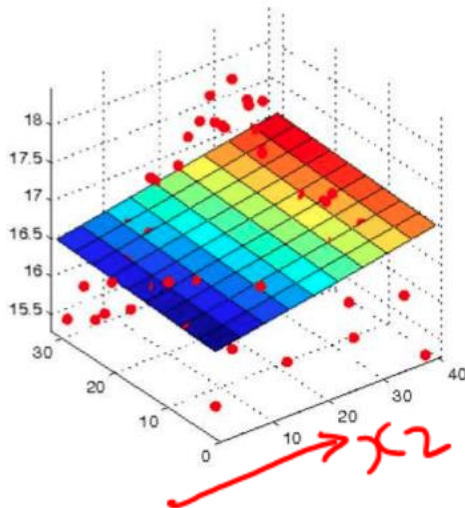
1   ...   m

$$\vec{\theta} \in \mathbb{R}^m$$

KEY: when the basis func are given,  
the problem of learning the  
parameters from data is still LR.

$$\hat{y} = \theta^T \mathbf{x}$$

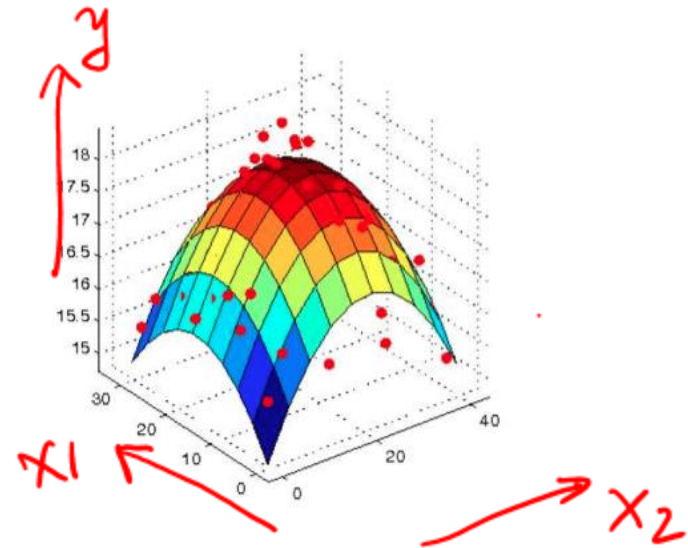
$$\phi(\mathbf{x}) = [1, x_1, x_2]$$



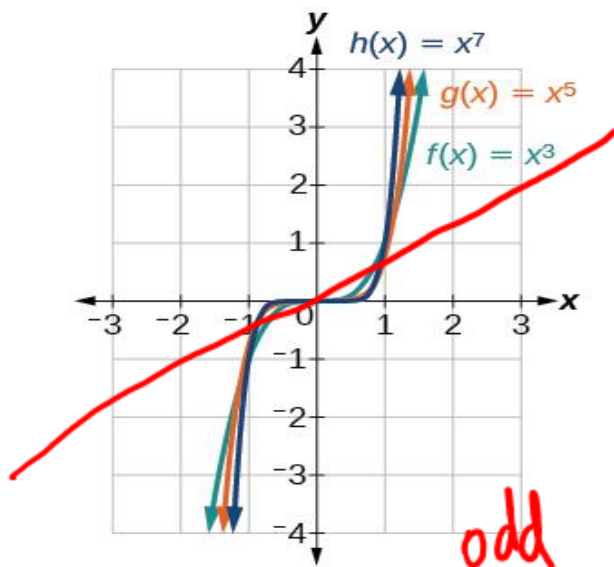
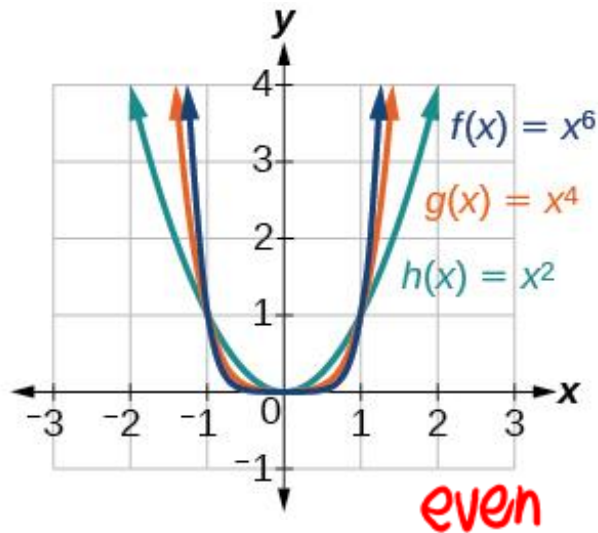
p=2

$$\hat{y} = \theta^T \phi(\mathbf{x})$$

$$\phi(\mathbf{x}) = [1, x_1, x_2, x_1^2, x_2^2] \quad , x_1, x_2$$



$$\varphi_j(x) = x^{j-1}$$



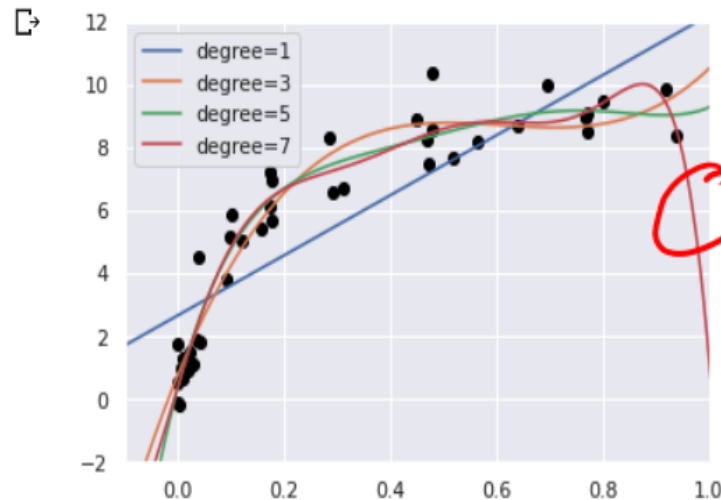
Notebook modified version: ( I will cell-run it)

[https://colab.research.google.com/drive/1gKEk0BuVORnpw\\_5jQ10wY1ZkA2mSXEAG?usp=sharing](https://colab.research.google.com/drive/1gKEk0BuVORnpw_5jQ10wY1ZkA2mSXEAG?usp=sharing)

```
%matplotlib inline
import matplotlib.pyplot as plt
import seaborn; seaborn.set() # plot formatting

X_test = np.linspace(-0.1, 1.1, 500)[:, None]

plt.scatter(X.ravel(), y, color='black')
axis = plt.axis()
for degree in [1, 3, 5, 7]:
    y_test = PolynomialRegression(degree).fit(X, y).predict(X_test)
    plt.plot(X_test.ravel(), y_test, label='degree={0}'.format(degree))
plt.xlim(-0.1, 1.0)
plt.ylim(-2, 12)
plt.legend(loc='best');
```



<https://colab.research.google.com/github/jakevdp/PythonDataScienceHandbook/blob/master/notebooks/05.06-Linear-Regression.ipynb>

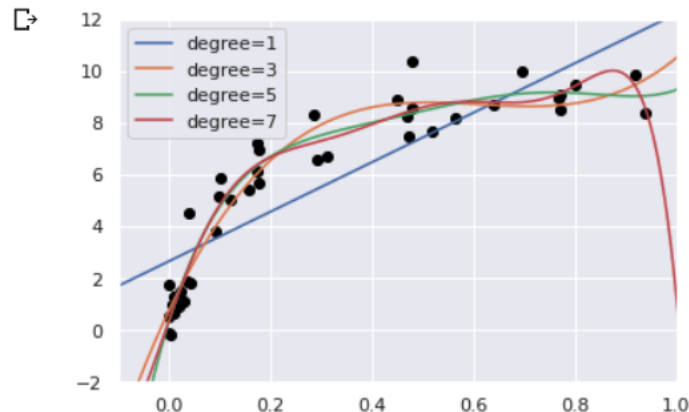
My google-colab modified version: ( I will cell-run it during class)

[https://colab.research.google.com/drive/1gKEk0BuVORnpw\\_5jQ10wY1ZkA2mSXEAG?usp=sharing](https://colab.research.google.com/drive/1gKEk0BuVORnpw_5jQ10wY1ZkA2mSXEAG?usp=sharing)

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# UVA CS 4774: Machine Learning

## Lecture 5: Linear Regression with Basis Functions Expansion

### Module 2

Dr. Yanjun Qi

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Department of Computer Science

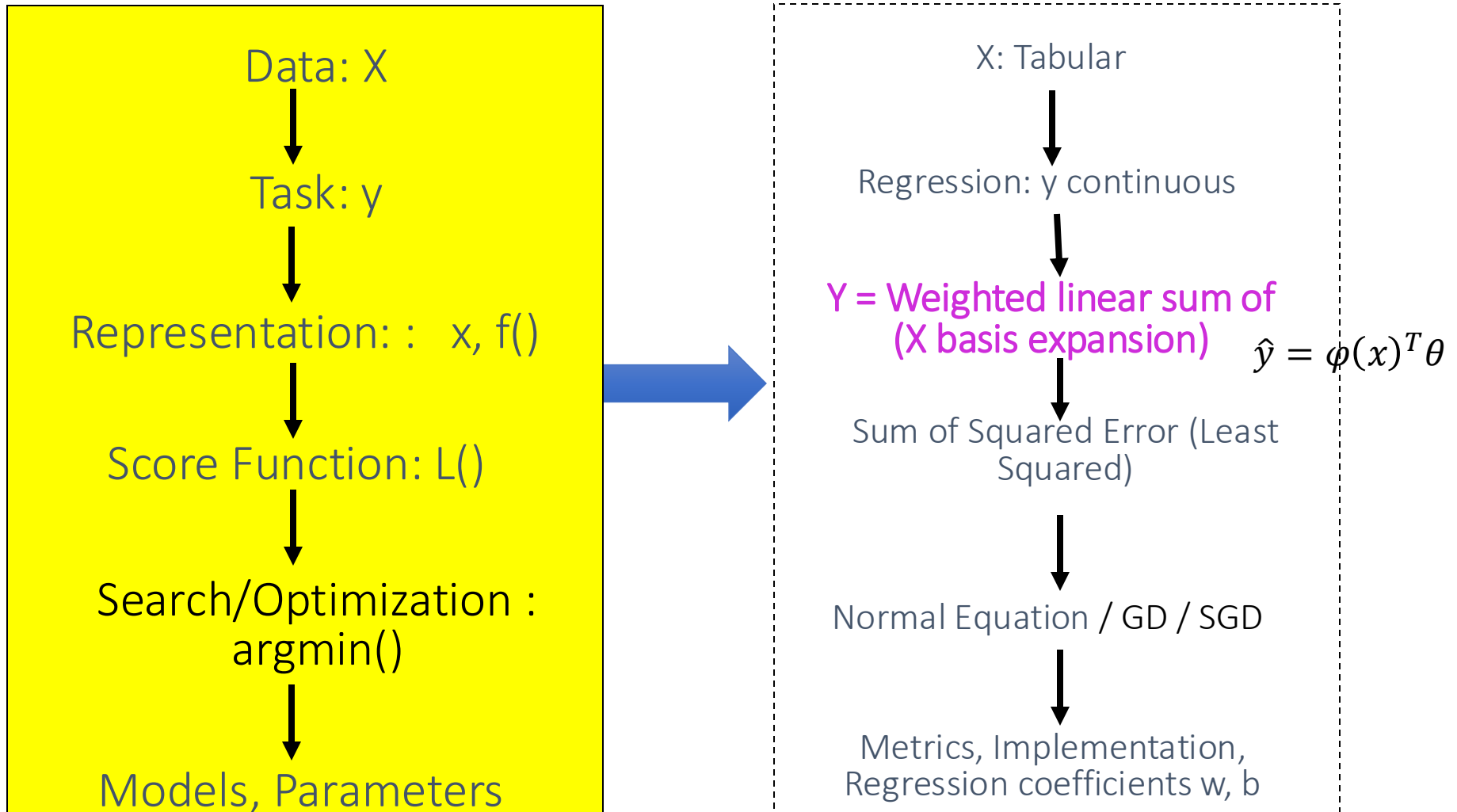
$$\hat{y} = \theta^T \mathbf{x}$$



$$\hat{y} = \theta^T \varphi(\mathbf{x})$$

Many Possible Basis functions

## Recap : Multivariate (non-) Linear Regression with Basis Expansion



# Many Possible Basis functions

- There are many basis functions, e.g.:

- Polynomial

$$\varphi_j(x) = x^{j-1}$$

$$[1, x, x^2, x^3, \dots, x^d]$$

- Radial basis functions

$$\varphi_j(x) = \exp\left(-\frac{(x - \mu_j)^2}{2\lambda^2}\right)$$

- Sigmoidal

$$\phi_j(x) = \sigma\left(\frac{x - \mu_j}{s}\right)$$

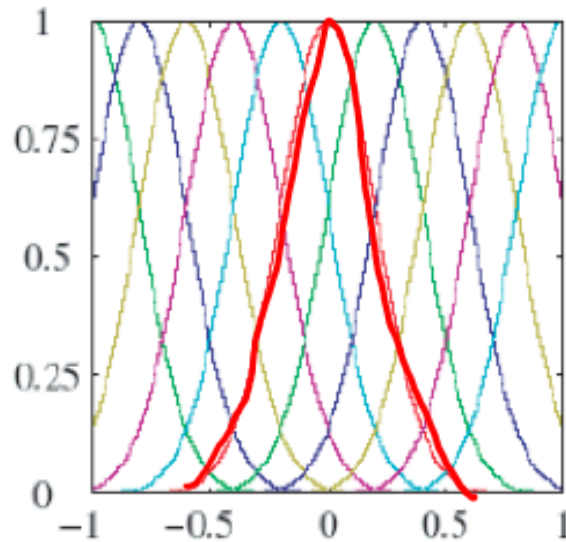
- Splines,

- Fourier,

- Wavelets, etc

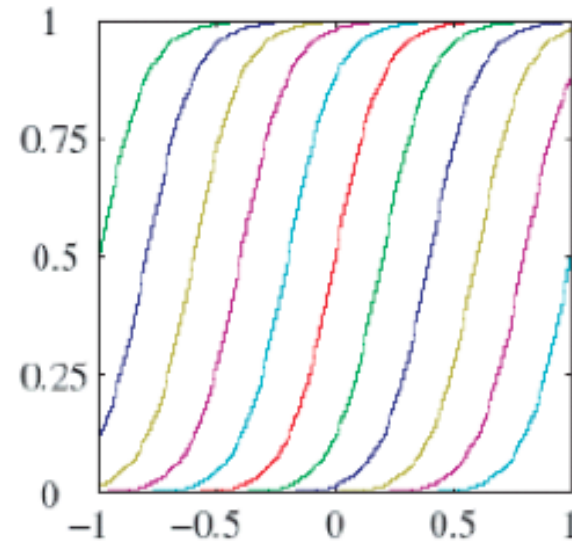
$$\varphi_j(x) = \exp\left(-\frac{(x - \mu_j)^2}{2\lambda^2}\right)$$

$$\phi_j(x) = \sigma\left(\frac{x - \mu_j}{s}\right)$$



RBF

"bell"-Shaped



Sigmoid

"S"-Shaped

**RBF = radial-basis function: a function which depends on the radial distance from a Centre point**

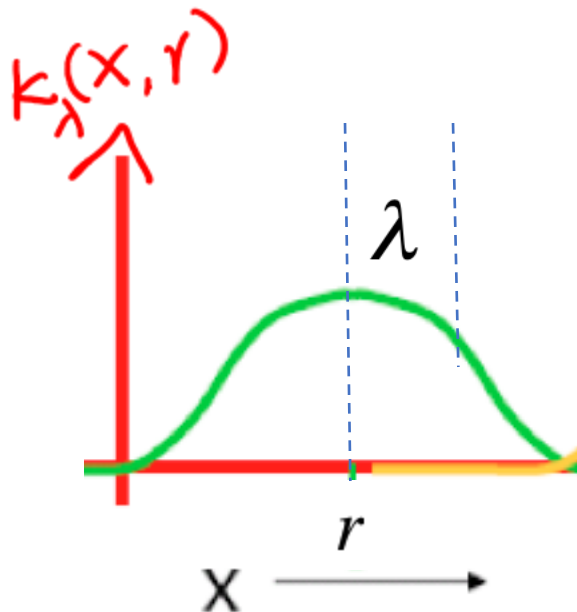
**Gaussian RBF** →  $K_{\lambda}(x, r) = \exp\left(-\frac{(x-r)^2}{2\lambda^2}\right)$

as distance from the center  $r$  increases, the output of the RBF decreases

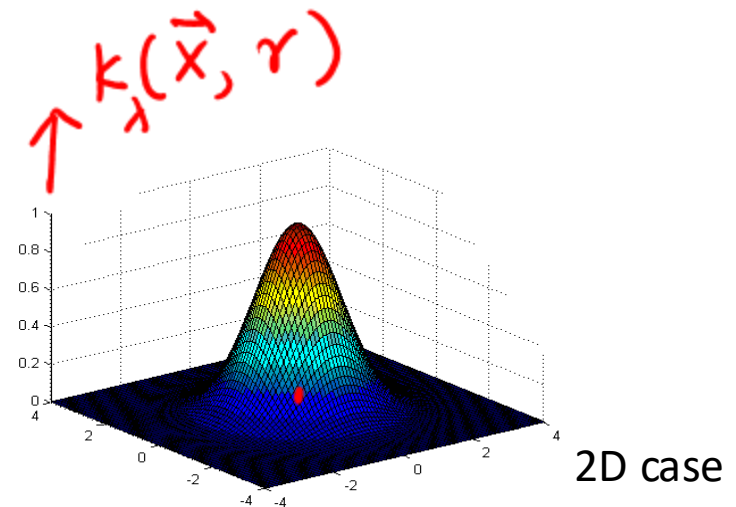
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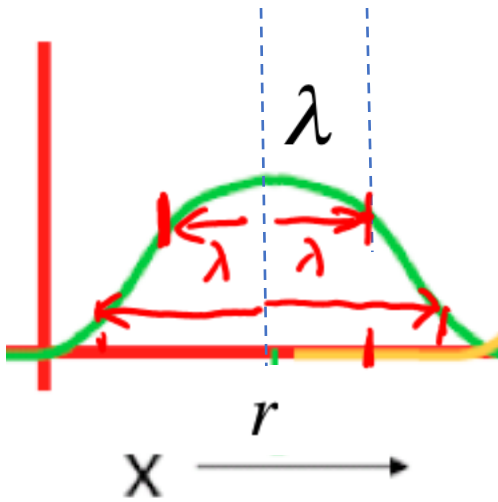
as distance from the center  $r$  increases, the output of the RBF decreases



1D case



2D case



$$K_{\lambda}(x, r) = \exp\left(-\frac{(x-r)^2}{2\lambda^2}\right)$$

[?]

$\gamma$

|                |                       |
|----------------|-----------------------|
| $X =$          | $K_{\lambda}(x, r) =$ |
| $r$            | 1                     |
| $r + \lambda$  | <u>0.6065307</u>      |
| $r + 2\lambda$ | 0.1353353             |
| $r + 3\lambda$ | 0.0001234098 $\sim 0$ |

0

$\begin{cases} X > r + 3\lambda \\ X < r - 3\lambda \end{cases}$

# LR with radial-basis functions

- E.g.: LR with RBF regression:

$$\hat{y} = \theta_0 + \sum_{j=1}^m \theta_j \varphi_j(x) = \varphi(x)^T \theta$$

$$\varphi_j(x) := K_{\lambda_j}(x, r_j) = \exp\left(-\frac{(x - r_j)^2}{2\lambda_j^2}\right)$$

hyperparameters of RBF basis functions  
(the predefined Centers and Width)

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$\varphi(x)$ : E.g. with four predefined RBF kernels

$$= \left[1, K_{\lambda_1}(x, r_1), K_{\lambda_2}(x, r_2), K_{\lambda_3}(x, r_3), K_{\lambda_4}(x, r_4)\right]^T$$

Users need to define the **hyperparameters** of RBF basis functions (the **predefined Centers and Width**)

$\varphi(x)$ : E.g. **with four predefined RBF** kernels

$$= \left[ 1, K_{\lambda_1}(x, r_1), K_{\lambda_2}(x, r_2), K_{\lambda_3}(x, r_3), K_{\lambda_4}(x, r_4) \right]^T$$

$$\theta^* = \left( \underline{\varphi}^T \varphi \right)^{-1} \varphi^T \bar{y}$$

e.g. (2) LR with radial-basis functions

- E.g.: LR with RBF regression:

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$$\vec{\theta} = [\theta_0, \theta_1, \theta_2, \theta_3, \theta_4]^T$$

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e.g. (2) LR with radial-basis functions

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$$\hat{y} = \theta_0 + \sum_{j=1}^m \theta_j \varphi_j(x) = \varphi(x)^T \theta$$

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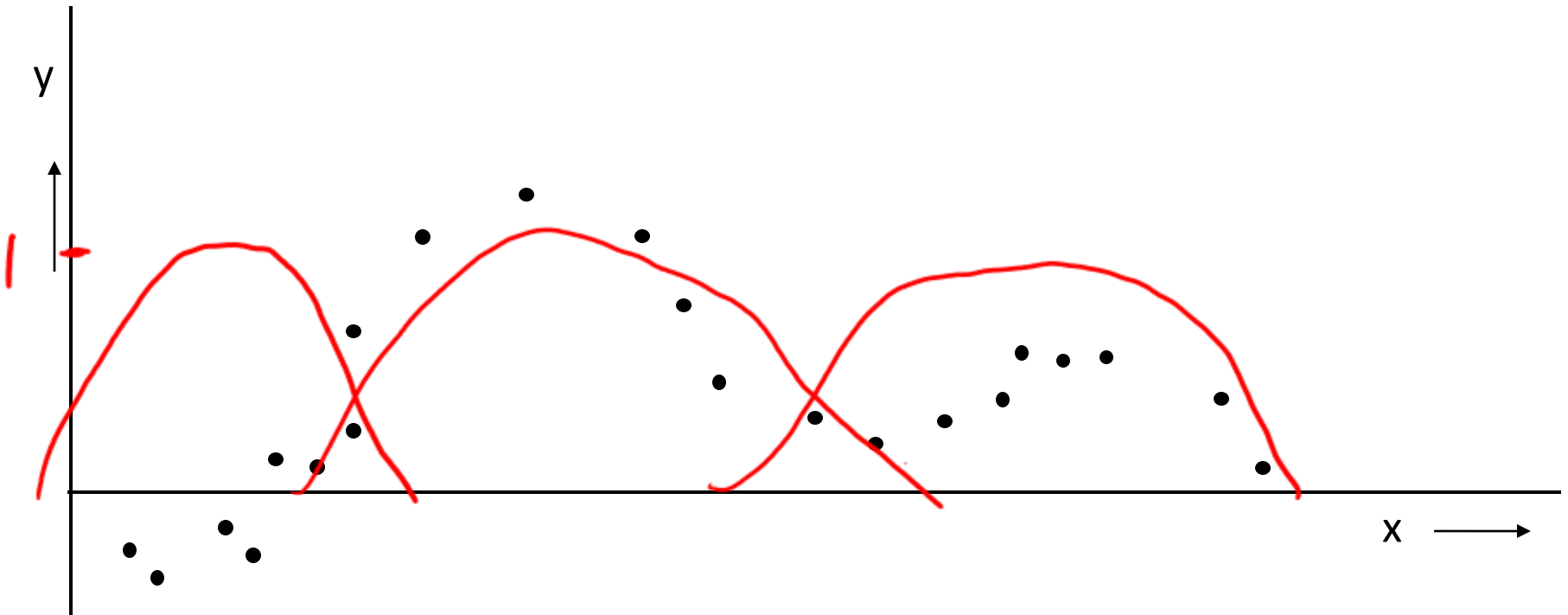
$$\theta^* = \left( \varphi^T \varphi \right)^{-1} \varphi^T \bar{y}$$

$$\vec{\theta} = \left[ \theta_0, \theta_1, \theta_2, \theta_3, \theta_4 \right]^T$$

$\begin{matrix} & r_1 & r_2 & r_3 & r_4 \\ & \lambda_1 & \lambda_2 & \lambda_3 & \lambda_4 \end{matrix}$

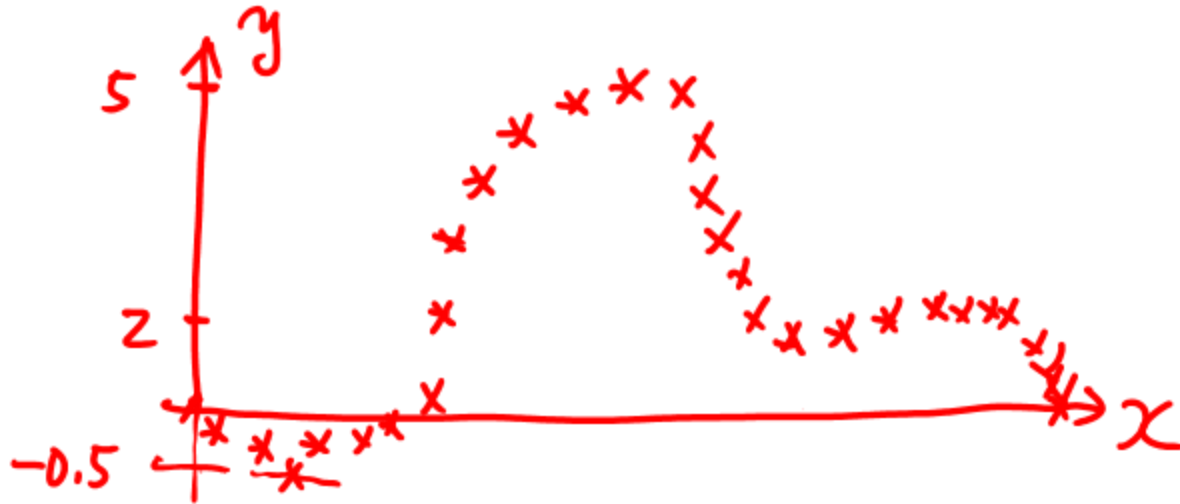
} hyper para

For example: I want to using 3 RBF basis functions to fit the following data points  
(I need to assume 3 predefined centres and width)



Given Training Data's scatter plot:

$$(x_i, y_i) \quad i=1, \dots, n$$



After my 3 RBF fit:

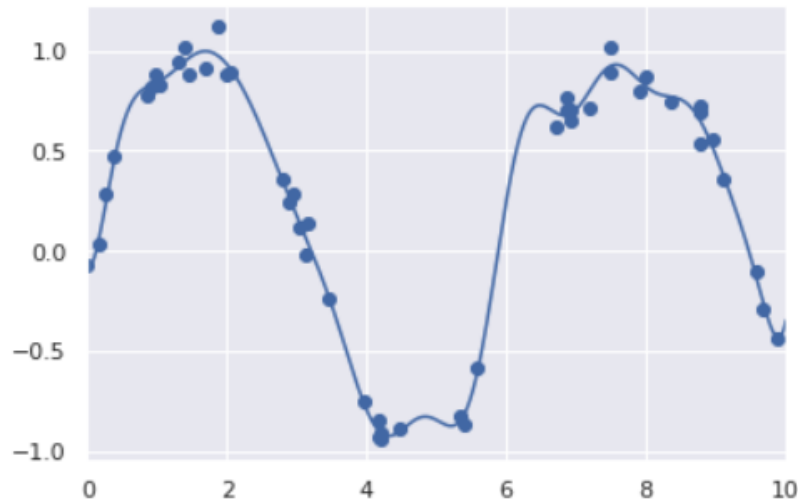
$$f(x) = \theta_0 - 0.5 k_{\lambda_1}(x, \underline{r_1}) + 5 k_{\lambda_2}(x, \underline{r_2}) + 2 k_{\lambda_3}(x, \underline{r_3})$$

<https://colab.research.google.com/drive/1BVcHUBYDO4AlwldcKmpmj5bIAbf7ISJb?usp=sharing>

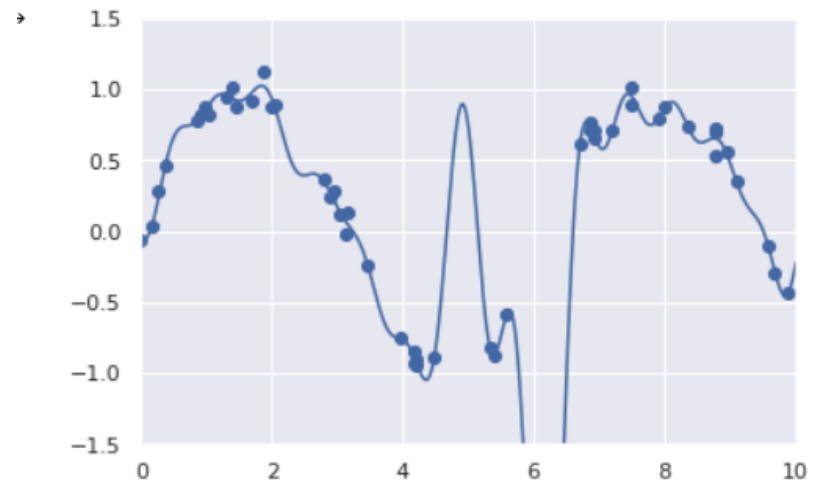
Modified from:

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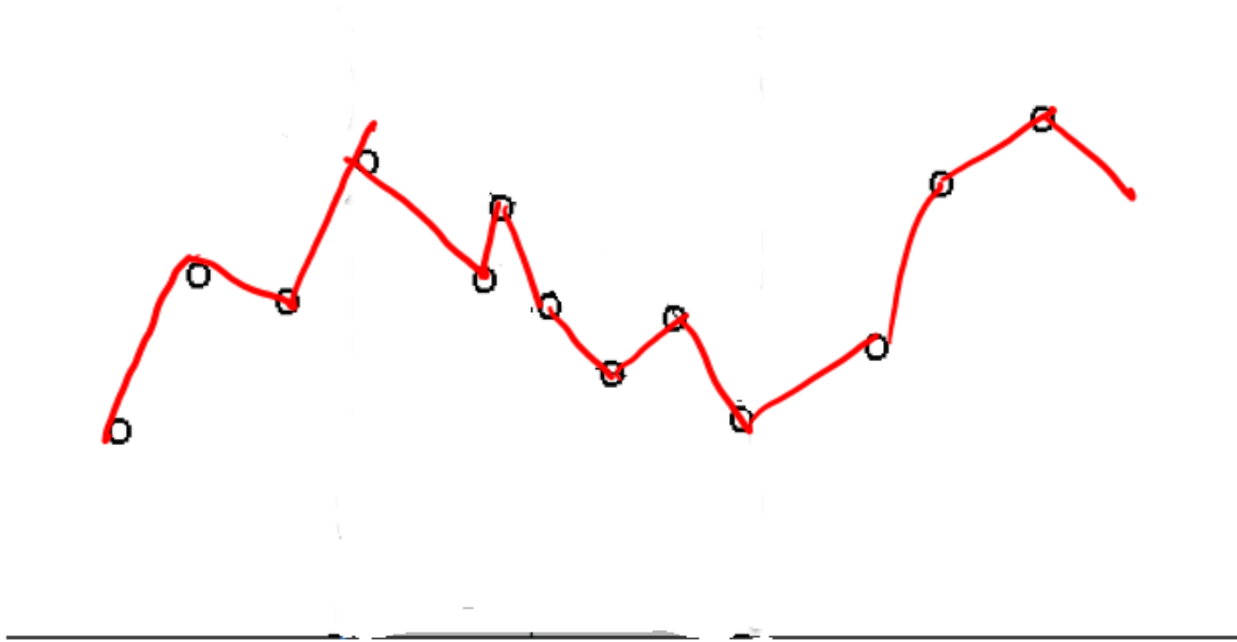
```
gauss_model = make_pipeline(GaussianFeatures(20),  
                             LinearRegression())  
gauss_model.fit(x[:, np.newaxis], y)  
yfit = gauss_model.predict(xfit[:, np.newaxis])  
  
plt.scatter(x, y)  
plt.plot(xfit, yfit)  
plt.xlim(0, 10);
```



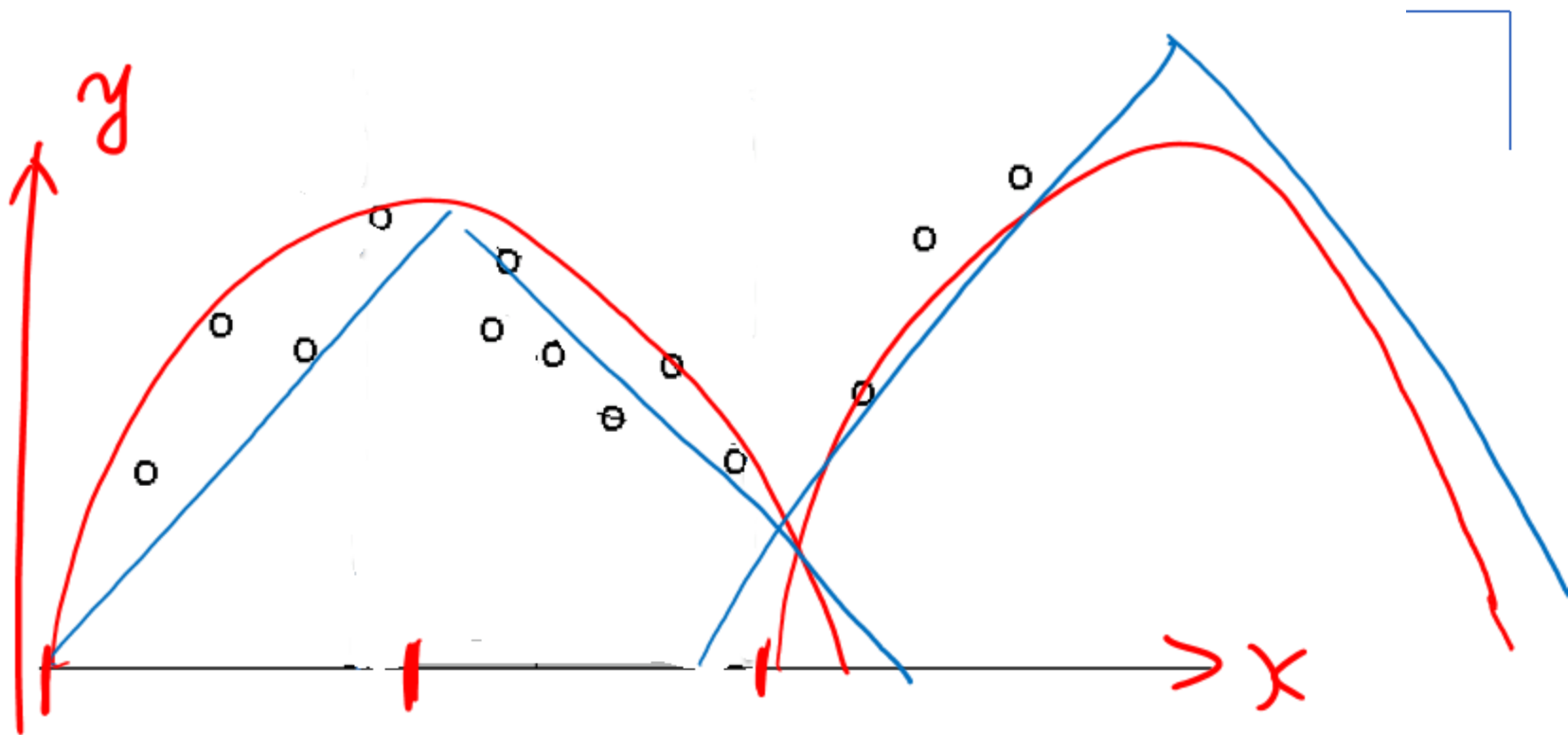
```
model = make_pipeline(GaussianFeatures(30),  
                       LinearRegression())  
model.fit(x[:, np.newaxis], y)  
  
plt.scatter(x, y)  
plt.plot(xfit, model.predict(xfit[:, np.newaxis]))  
  
plt.xlim(0, 10)  
plt.ylim(-1.5, 1.5);
```



Extra: even more possible Basis Function:  
RBF, or **Piecewise Linear** based?

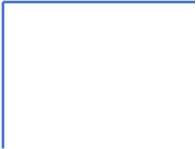


e.g. Even more possible Basis Func?



# Thank You



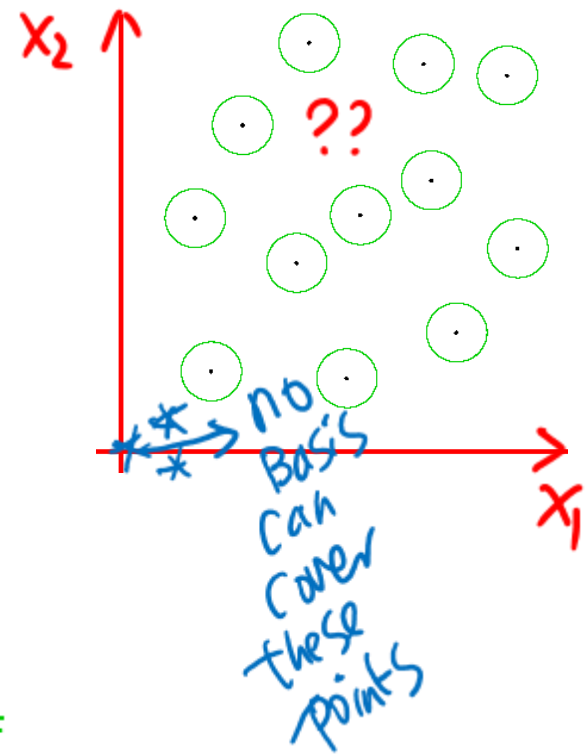
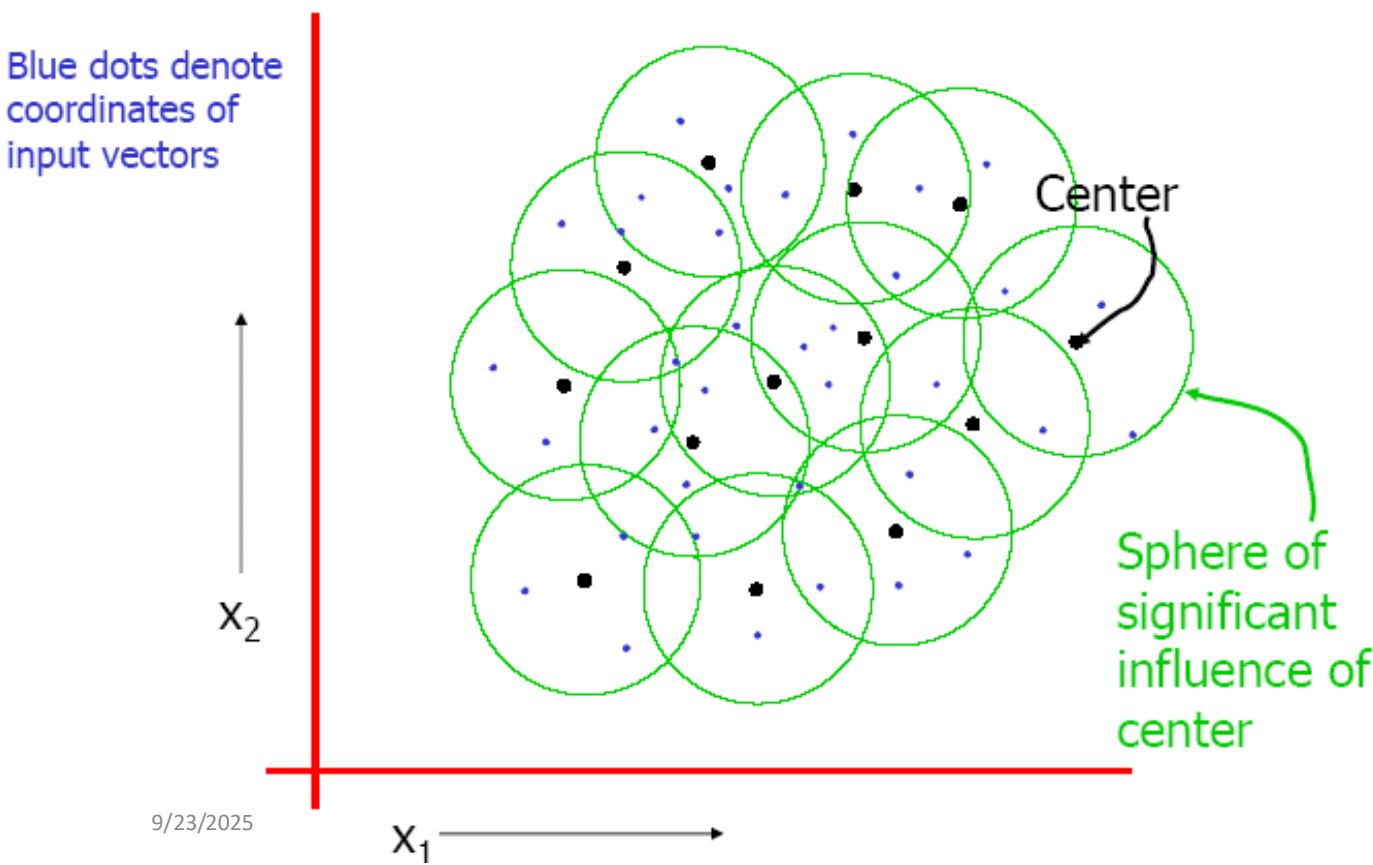


# Extra

# Extra: e.g. 2D Good and Bad RBF Basis

*Contour view*

- A good set of 2D predefined RBF basis
- A Bad set of predefined 2D RBFs



# Extra: Nonparametric Regression Models

- K-Nearest Neighbor (KNN) and Locally weighted linear regression are **non-parametric** algorithms.
- The (unweighted) linear regression algorithm that we saw earlier is known as a **parametric** learning algorithm
  - because it has a fixed, finite number of parameters which are fit to the data;
  - Once we've fit the  $\theta$  and stored them away, we no longer need to keep the training data around to make future predictions.
  - In contrast, to make predictions using KNN or locally weighted linear regression, we need to keep the entire training set around.
- The term "**non-parametric**" (roughly) refers to the fact that the amount of knowledge we need to keep, in order to represent the hypothesis grows with linearly the size of the training set.